

Package ‘cartogramR’

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Title Continuous Cartogram

Description Procedures for making continuous cartogram. Procedures available are:
flow based cartogram (Gastner & Newman (2004) <[doi:10.1073/pnas.0400280101](https://doi.org/10.1073/pnas.0400280101)>),
fast flow based cartogram (Gastner, Seguy & More (2018) <[doi:10.1073/pnas.1712674115](https://doi.org/10.1073/pnas.1712674115)>),
rubber band based cartogram (Dougenik et al. (1985)
<[doi:10.1111/j.0033-0124.1985.00075.x](https://doi.org/10.1111/j.0033-0124.1985.00075.x)>).

Depends R (>= 3.5.0)

Imports sf, data.table, cleancall

LinkingTo cleancall

Suggests lwgeom

SystemRequirements FFTW (>=3.3.1); possible package: fftw-devel (rpm),
libfftw3-dev (deb) or fftw (brew).

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Contents

as.sf	2
as.sf.cartogramR	3

as.sfc	3
as.sfc.cartogramR	4
as.sfmultipolygon	4
cartogramR	5
cartogramR_options	6
check_ring_dir	8
dist_between_vertices	9
france_dept	9
france_rivers	10
from_coord_polygon	10
grid_analysis	11
make_layer	12
plot.cartogramR	12
plot.dbv.cartogramR	13
plot.gridanalysis.cartogramR	14
precartogramR	15
print.cartogramR	16
print.summary.cartogramR	17
residuals.cartogramR	17
summary.cartogramR	18
summary.dbv.cartogramR	19
summary.gridanalysis.cartogramR	20
to_coord_polygon	21
usa	21
warp_features	22

Index 23

as.sf	<i>Coerce an object to a sf object</i>
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Description

Coerce an object to a sf object

Usage

```
as.sf(x, ...)
```

Arguments

x	object to be coerced
...	arguments passed to or from other methods.

Value

an sf object

as.sf.cartogramR	<i>Coerce a cartogramR to a sf object</i>
------------------	---

Description

Coerce a cartogramR to a sf object returning the sf object used to construct the cartogram with the cartogram as geometry and some more attributes

Usage

```
## S3 method for class 'cartogramR'  
as.sf(x, ...)
```

Arguments

x	a cartogramR object
...	arguments passed to or from other methods.

Value

a sf object including all the data (attributes) contained in the original sf object used to construct the cartogram and

- original areas of region (orig_area)
- final/deformed areas of region (final_area)
- target areas of region (target_area)
- original centers (x_orig_centers and y_orig_centers)
- final centers (x_final_centers and y_final_centers)

as.sfc	<i>Coerce an object to a sfc object</i>
--------	---

Description

Coerce an object to a sfc object

Usage

```
as.sfc(x, ...)
```

Arguments

x	object to be coerced
...	arguments passed to or from other methods.

Value

a sfc object

as.sfc.cartogramR *Coerce a cartogramR to a sfc object*

Description

Coerce a cartogramR to a sfc object extracting the component cartogram of the cartogramR object

Usage

```
## S3 method for class 'cartogramR'
as.sfc(x, ...)
```

Arguments

x a cartogramR object
 ... arguments passed to or from other methods.

Value

a sfc object

as.sfmultipolygon *Transform a sf object with several rows (polygons) by region to an sf object with one row by region and thus one multipolygon by region*

Description

Transform a sf object with several rows (polygons) by region to an sf object with one row by region and thus one multipolygon by region

Usage

```
as.sfmultipolygon(data, idregion, closepolygon = FALSE)
```

Arguments

data a sf object
 idregion a character string which indicates the name of the column (in data object) which contains the region identifier.
 closepolygon a boolean (default to FALSE) if TRUE it controls if polygons are closed and if not add the first vertice at the end.

Value

a sf object with one row by region and one multipolygon by region.

cartogramR	<i>Make a continuous cartogram (density equalizing maps)</i>
------------	--

Description

Make a continuous cartogram (density equalizing maps)

Usage

```
cartogramR(
  data,
  count,
  method = c("gsm", "gn", "dcn", "GastnerSeguyMore", "GastnerNewman",
    "DougenikChrismanNiemeyer"),
  options = NULL
)
```

Arguments

data	a sf object which contains at least two columns: obviously a geometry column (giving the map) and a column which contains a count by region (leading to a density by region, density to be equalized by deformation). Each row of data is a region and contains the simple feature geometry of type POLYGON or MULTIPOLYGON. Polygon ring directions are not checked but exterior ring must counter clockwise and holes clockwise (use option <code>check_ring_dir</code> of <code>sf::st_read</code> to achieve the right orientation of ring direction on import or use <code>check_ring_dir</code> function)
count	a character string which indicates the name of the column (in data object) which contains the count by region.
method	the method to be used, can be one of the following: <code>gsm</code> or <code>GastnerSeguyMore</code> (default), <code>gn</code> or <code>GastnerNewman</code> , <code>dcn</code> or <code>DougenikChrismanNiemeyer</code> .
options	a named list given to <code>cartogramR_options</code> function which process options see <code>cartogramR_options</code> for details. Default to <code>NULL</code> .

Value

A `cartogramR` object: a list with the following components:

- `cartogram`: a sf object (in the same order of data or sorted by `idregion` see `reordered` argument) which contains the initial data (without the geometry) with three additional columns (`orig_area`: original areas of regions, `final_area`: final areas of regions in the cartogram and `target_areas` the targeted area) and a geometry part which is the cartogram (ie the initial polygons after deformation)
- `orig_centers`: the initial centers calculated with `sf::st_point_on_surface`
- `final_centers`: the centers after deformation

- `gridx`: (for flow-based method) final grid (x-axis) if requested (see [cartogramR_options](#) for details).
- `gridy`: (for flow-based method) final grid (y-axis) if requested (see [cartogramR_options](#) for details). with additional attributes.

References

- Dougenik, J., Chrisman, R. & Niemeyer, D. (1985). An algorithm to construct continuous area cartograms. *Professional Geographer* **37**: 75-81.
- Gastner, M. & Newman, M.E.J. (2004). Diffusion-based method for producing density equalizing maps. *Proc. Natl. Acad. Sci. USA*, **101**:7499-7504
- Gastner, M., Seguy, V. & More, P. (2018). Fast flow-based algorithm for creating density-equalizing map projections. *Proceedings of the National Academy of Sciences USA*, **115**:E2156-E2164, website: [go-cart](#)

Examples

```
data(usa)
carto <- cartogramR(usa, "electors64")
plot(carto)
summary(carto)
```

`cartogramR_options` *Set the options of [cartogramR](#) in the correct format*

Description

Set the options of [cartogramR](#) in the correct format

Usage

```
cartogramR_options(
  options,
  method = c("gsm", "gn", "dcn", "GastnerSeguyMore", "GastnerNewman",
             "DougenikChrismanNiemeyer")
)
```

Arguments

`options` a named list with some (or all) the following components:

- `maxit`: (all method) the maximum number of iterations, default to 50.
- `maxit_internal`: ("gsm" or "gn") the maximum number of internal iterations, default to 10000.
- `absrel`: (all method) boolean, if TRUE relative convergence if FALSE absolute convergence (default to TRUE)

- **abserror**: (all method) Areas on cartogram differ at most by an (absolute value of) error of abserror. That is, $\max_{polygons} |area_{on_cartogram} - target_area| \leq abserror$ (default to 10000)
- **abstol**: ("dcn") the absolute convergence error tolerance: $\max_{polygons} |area(i) - area(i - 1)|$ default to 1000
- **releror**: (all method) Areas on cartogram differ at most by an (absolute value of) relative error of releror. That is, $\max_{polygons} |area_{on_cartogram} / target_area - 1| \leq releror$ (default to 0.01)
- **reltol**: ("dcn") the absolute convergence tolerance: $\max_{polygons} abs((area(i) - area(i - 1)) / area(i - 1))$ default to 1e-3
- **L**: ("gsm" or "gn") integer, gives the value of L (default is 512), must be a power of two (for fftw)
- **mp**: (all method) if a region contains exactly zero population, it will be replaced by mp times the smallest (strictly) positive population in any region (default to 0.2)
- **pf**: ("gsm" or "gn") Determines space between map and boundary (default to 1.5)
- **sigma**: ("gsm" or "gn") Width of Gaussian blur to smoothen the density (default to 5)
- **center**: ("gsm" or "gn") either a character string (only possible choices are "centroid" or "point_on_surface") or a function. If the object is a function, it will be used to calculate the "center" of polygons; "point_on_surface" will use the function `sf::st_point_on_surface` while "centroid" (the default) will use `sf::st_centroid`.
- **verbose**: (all method) integer giving the verbosity level (default to 0, not verbose)
- **grid**: ("gsm" or "gn") boolean, if TRUE export the final grid from flow algorithm (default to TRUE). Setting to FALSE
- **check.ring.dir**: (all method) boolean, if TRUE controls polygons orientation (default to TRUE)
- **check.only**: (all method) boolean, if TRUE control only polygons orientation and no replacement is done (default to FALSE)

method the method to be used, can be one of the following: gsm or GastnerSeguyMore (default), gn or GastnerNewman, dcn or DougenikChrismanNiemeyer.

Value

a list to be processed by `cartogramR`

References

- Dougenik, J., Chrisman, R. & Niemeyer, D. (1985). An algorithm to construct continuous area cartograms. *Professional Geographer* **37**: 75-81.
- Gastner, M. & Newman, M. E. J. (2004). Diffusion-based method for producing density equalizing maps. *Proc. Natl. Acad. Sci. USA*, **101**:7499-7504

- Gastner, M., Seguy, V. & More, P. (2018). Fast flow-based algorithm for creating density-equalizing map projections. *Proceedings of the National Academy of Sciences USA*, **115**:E2156-E2164

Examples

```
data(usa)
carto1 <- cartogramR(usa, "electors64", options=list(verbose=1, L=256))
plot(carto1)
```

check_ring_dir	<i>Polygon rings directions are checked and corrected if asked.</i>
----------------	---

Description

Polygon ring are seen from above: exterior ring counter clockwise, holes clockwise

Usage

```
check_ring_dir(polygons, check.only = TRUE)
```

Arguments

polygons	a sfc object which contains simple feature geometry of types POLYGON or MULTIPOLYGON
check.only	a boolean which indicates if the function only checks the ring direction (check.only=TRUE) or checks and corrects the polygon direction (check.only=FALSE)

Value

Either a logical vector which indicates if line i of polygons is in the right direction (TRUE) or not or the corrected sfc object

Examples

```
data(usa)
all(check_ring_dir(sf::st_geometry(usa), check.only=TRUE))
```

dist_between_vertices *Analyse some of the grid options*

Description

Analyse some of the grid options

Usage

```
dist_between_vertices(data)
```

Arguments

data a sf object to be used in cartogram.

Value

a 'dbv.cartogramR' object which is a data-table which contains distance between vertices ('dbv') and polygons names ('L1', 'L2', 'L3') inherited from [sf::st_coordinates]

Examples

```
data(usa)
dbv <- dist_between_vertices(data=usa)
summary(dbv)
```

france_dept *Map of the population of mainland France (year 2018)*

Description

This data set is a basemap of mainland France with the population in 2018 (pop2018), the number of physicians in 2018 (n_physicians), the number of general practitioner in 2018 (n_gp) and the number of general practitioner for 100000 inhabitants in 2018 (n_gp_per100000) in each department (dept_name or id).

Usage

```
data(france_dept)
```

Format

A sf object containing 8 columns of data and the geometry Projected CRS: RGF93 / Lambert-93 (EPSG : 2154)

Source

https://www.data.gouv.fr/fr/datasets/admin-express/#_

References

- https://www.insee.fr/fr/statistiques/2012713#tableau-TCRD_004_tab1_departements
- https://www.insee.fr/fr/statistiques/2012677#tableau-TCRD_068_tab1_departements

france_rivers

Map of french rivers of mainland France

Description

This data set is a basemap of mainland french rivers (name or id).

Usage

```
data(france_rivers)
```

Format

A sf object containing 2 columns of data and the geometry Projected CRS: RGF93 / Lambert-93 (EPSG : 2154)

Source

<https://geoservices.ign.fr/telechargement-api>

from_coord_polygon

Transform from coordinates system used in the polygons to coordinates system used in flow based cartogram

Description

Apply the mapping from the coordinates system used in the polygons (characterised by the CRS) to the coordinates system used in flow based cartogram

Usage

```
from_coord_polygon(coord, carto)
```

Arguments

coord	a vector of length 2 or a two columns matrix containing xy coordinates to transform
carto	a cartogramR object

Value

a vector of length 2 or a two columns matrix containing xy coordinates in the coordinate systems of polygons used to build the cartogram

Examples

```
data(usa)
carto <- cartogramR(usa, "electors64")
from_coord_polygon(c(-0.007, -0.348), carto)
```

grid_analysis	<i>Analyse some of the grid options</i>
---------------	---

Description

Analyse some of the grid options

Usage

```
grid_analysis(data, gridpower2 = 8:11, pf = 1.5, verbose = FALSE)
```

Arguments

data	a sf object to be used in cartogram.
gridpower2	a vector of exponent (to be raised at the power of 2) that gives the log2(size) of the grid (default to '8:11')
pf	Determines space between map and boundary (default to 1.5)
verbose	a boolean object to set on verbose mode (default to 'TRUE')

Value

a 'gridanalysis.cartogramR' object which is a matrix

Examples

```
data(usa)
ga <- grid_analysis(data=usa, gridpower2=4:8, verbose=TRUE)
summary(ga)
```

make_layer	<i>Make a layer</i>
------------	---------------------

Description

Create a sfc object containing final centers, original centers, centers displacement, original graticule or final graticule.

Usage

```
make_layer(
  x,
  type = c("final_centers", "original_centers", "centers_translation", "final_graticule",
           "original_graticule")
)
```

Arguments

x	a cartogramR object
type	a character string giving the type of layer: - "final_centers": if method is dcn, sf::st_centroid is applied on deformed/cartogram region ; if method is gsm or gn (ie flow based), initial "centers" are calculated and the cartogram deformation is applied on these "centers" giving the final_centers. - "original_centers" if method is dcn, sf::st_centroid is applied on original regions); if method is gsm or gn (ie flow based), initial "centers" are calculated using cartogramR center option see cartogramR_options . - "centers_translation" linestring giving the movement of centers due to the deformation used to have the cartogram - "final_graticule" (method gsm or gn) graticule obtained by the cartogram algorithm - "original_graticule" (method gsm or gn) graticule used by the cartogram algorithm

Value

a sfc object

plot.cartogramR	<i>Plot a cartogram object</i>
-----------------	--------------------------------

Description

Plot a cartogram object

Usage

```
## S3 method for class 'cartogramR'
plot(x, ...)
```

Arguments

x a cartogram object
 ... arguments passed to or from other methods.

Value

No return value, called for side effects

Examples

```
data(usa)
carto <- cartogramR(usa, "electors64")
plot(carto)
```

plot.dbv.cartogramR *Plot a dbv.cartogram object*

Description

Plot a dbv.cartogram object

Usage

```
## S3 method for class 'dbv.cartogramR'
plot(x, which = 1:2, ask = TRUE, key = TRUE, last = 10, probminx = 0.9, ...)
```

Arguments

x a dbv.cartogram object
 which if a subset of the plots is required, specify a subset of the numbers 1:2
 ask logical; if TRUE, the user is asked before each plot, see [par\(ask=.\)](#)
 key logical; if TRUE, a legend is drawn
 last draw the density of distance between vertices for the last coordinates
 probminx the sample quantiles (of distance between vertices) corresponding to the probability is used as a minimum of x-axis for the density plot (used only if last is NULL)
 ... arguments passed to or from other methods.

Details

The first plot is the density of distance between consecutive vertice by region. Only the upper quantiles are shown. The second plot is a barplot by region of the number of vertice divided by the perimeter of the region

Value

No return value, called for side effects

Examples

```
data(usa)
precarto <- precartogramR(usa, method="dcn")
plot(precarto)
```

```
plot.gridanalysis.cartogramR
```

Plot a gridanalysis.cartogram object

Description

Plot a gridanalysis.cartogram object

Usage

```
## S3 method for class 'gridanalysis.cartogramR'
plot(
  x,
  nthsmallest = 5,
  redrawxaxis = TRUE,
  type = "b",
  xlab = NULL,
  ylab = NULL,
  ylim = c(0, 20),
  ...
)
```

Arguments

x	a gridanalysis.cartogram object
nthsmallest	plot only the nthsmallest values among all polygons
redrawxaxis	if TRUE redraw ticks and labels of x axis at grid size on log scale
type	character string (length 1 vector) or vector of 1-character strings indicating the type of plot for each polygons, see graphics::matplot for all possible types.
xlab	titles for x axis, as in graphics::matplot .
ylab	titles for y axis, as in graphics::matplot .
ylim	ranges of y axis, as in graphics::matplot .
...	arguments passed to or from other methods.

Value

No return value, called for side effects

Examples

```
data(usa)
precarto <- precartogramR(usa, method="gsm", pf=1.2, verbose=TRUE)
plot(precarto)
```

```
precartogramR      Make a pre cartogram analysis
```

Description

Make a pre cartogram analysis

Usage

```
precartogramR(
  data,
  method = c("gsm", "gn", "dcn", "GastnerSeguyMore", "GastnerNewman",
             "DougenikChrismanNiemeyer"),
  gridpower2 = 8:11,
  pf = 1.5,
  verbose = FALSE
)
```

Arguments

data	a sf object which contains at least two columns: obviously a geometry column (giving the map) and a column which contains a count by region (leading to a density by region, density to be equalized by deformation). Each row of data is a region and contains the simple feature geometry of type POLYGON or MULTIPOLYGON. Polygon ring directions are not checked but exterior ring must counter clockwise and holes clockwise (use option <code>check_ring_dir</code> of <code>sf::st_read</code> to achieve the right orientation of ring direction on import or use <code>check_ring_dir</code> function)
method	the method to be used, can be one of the following: <code>gsm</code> or <code>GastnerSeguyMore</code> (default), <code>gn</code> or <code>GastnerNewman</code> , <code>dcn</code> or <code>DougenikChrismanNiemeyer</code> .
gridpower2	a vector of exponent (to be raised at the power of 2) that gives the $\log_2(\text{size})$ of the grid (default to 8:11); meaningful for method <code>gsm</code> or <code>GastnerSeguyMore</code> (default), <code>gn</code> or <code>GastnerNewman</code>
pf	Determines space between map and boundary (default to 1.5); meaningful for method <code>gsm</code> or <code>GastnerSeguyMore</code> (default), <code>gn</code> or <code>GastnerNewman</code>
verbose	a boolean object to set on verbose mode (default to FALSE); meaningful for method <code>gsm</code> or <code>GastnerSeguyMore</code> (default), <code>gn</code> or <code>GastnerNewman</code>

Value

either a `dbv.cartogramR` object (if method is `dcn` or `DougenikChrismanNiemeyer`) see [dist_between_vertices](#) for details or a `gridanalysis.cartogramR` (if method is `gsm` or `GastnerSeguyMore` (default), `gn` or `GastnerNewman`) see [grid_analysis](#) for details

References

- Dougenik, J., Chrisman, R. & Niemeyer, D. (1985). An algorithm to construct continuous area cartograms. *Professional Geographer* **37**: 75-81.
- Gastner, M. & Newman, M.E.J. (2004). Diffusion-based method for producing density equalizing maps. *Proc. Natl. Acad. Sci. USA*, **101**:7499-7504
- Gastner, M., Seguy, V. & More, P. (2018). Fast flow-based algorithm for creating density-equalizing map projections. *Proceedings of the National Academy of Sciences USA*, **115**:E2156-E2164

Examples

```
data(usa)
precarto <- precartogramR(usa)
plot(precarto)
summary(precarto)
```

```
print.cartogramR      Print a cartogram object
```

Description

Print a cartogram object

Usage

```
## S3 method for class 'cartogramR'
print(x, ...)
```

Arguments

```
x          a cartogramR object
...        arguments passed to or from other methods.
```

Value

No return value, called for side effects

```
print.summary.cartogramR
```

Print a summary of a cartogram object

Description

Print a summary of a cartogram object

Usage

```
## S3 method for class 'summary.cartogramR'  
print(x, ...)
```

Arguments

`x` a `summary.cartogramR` object
`...` arguments passed to or from other methods. The following argument is available at this level : `digits`, the number of significant digits to use when printing.

Value

`x`.

Examples

```
data(usa)  
carto <- cartogramR(usa, "electors64")  
summary(carto)
```

```
residuals.cartogramR
```

Errors of a cartogram object

Description

Errors of a cartogram object

Usage

```
## S3 method for class 'cartogramR'  
residuals(object, ...)
```

Arguments

object a cartogramR object

... arguments passed to or from other methods. The following arguments are available: - type; a character string giving the type of residuals (see details; can be abbreviated) - "relative error" - "absolute error" - "symmetric difference" - center; a character string giving the type of center (can be abbreviated): - "point_on_surface" ([sf::st_point_on_surface](#) applied on original and on deformed/cartogram region). - "deformed_center" (the center function, see [cartogramR_options](#), is applied on region and this center follows the deformation giving the center on the deformed/cartogram region) - "centroid" (centroid of original and deformed/cartogram region). - initial_data; the initial sf object given as input of cartogramR. Only needed for symmetric differences residuals.

Details

The error vector contains the values of the differences between actual area of regions in the cartogram and theoretical area (obtained with conservation of total area and constant density over region in the final cartogram)

Relative error are the error vector divided by the theoretical area

Symmetric difference are the symmetric difference between actual area of regions in the cartogram and the original area. Each region is scaled to have an area equal to 1 and centered around the chosen center.

Value

A numeric vector which contains for each region observed area minus theoretical area

Examples

```
data(usa)
carto <- cartogramR(usa, "electors64")
residuals(carto)
```

summary.cartogramR *Summary of a cartogram object*

Description

Summary of a cartogram object

Usage

```
## S3 method for class 'cartogramR'
summary(object, ...)
```

Arguments

object	a cartogramR object
...	arguments passed to or from other methods. The following arguments are available: - digits integer, used for number formatting with signif if not specified (i.e., [missing](.), [signif]() will not be called anymore (since \R >= 3.4.0, where the default has been changed to only round in the print and format methods). - quantile.type integer code used in quantile(*, type=quantile.type). - center character string code used in residuals.cartogramR . - initial_data; the initial sf object given as input of cartogramR. Only needed for symmetric differences residuals.

Value

A summary.cartogramR object: a list with the following components:

- qrr, the summary of absolute relative residuals
- qres, the summary of absolute residuals
- qsymdiff, the summary of all pairwise symmetric difference between two scaled (multi)polygons representative of two regions. These residuals are calculated only if initial_data argument is provided.

Examples

```
data(usa)
carto <- cartogramR(usa, "electors64")
summary(carto)
```

```
summary.dbv.cartogramR
```

Summary of a dbv.cartogram object

Description

Summary of a dbv.cartogram object

Usage

```
## S3 method for class 'dbv.cartogramR'
summary(object, ...)
```

Arguments

object a dbv.cartogramR object
 ... arguments passed to or from other methods.

Value

a data-table which contains by region (L3)

- the sample quantiles corresponding to the probability 0.8, 0.85, ...,1
- the total number of vertices divided by the perimeter of the region (the sum of all polygons perimeter of the region, NbyPerim)

Examples

```
data(usa)
dbv <- dist_between_vertices(data=usa)
summary(dbv)
```

summary.gridanalysis.cartogramR

Summary of a gridanalysis.cartogram object

Description

Summary of a gridanalysis.cartogram object

Usage

```
## S3 method for class 'gridanalysis.cartogramR'
summary(object, ...)
```

Arguments

object a gridanalysis.cartogramR object
 ... arguments passed to or from other methods.

Value

A vector which indicate the grid size necessary to have more than steps grid points in each polygon

Examples

```
data(usa)
ga <- grid_analysis(data=usa, gridpower2=4:9)
summary(ga)
```

to_coord_polygon	<i>Transform from coordinates system used in flow based cartogram to coordinates system used in the polygons</i>
------------------	--

Description

Apply the mapping from the coordinates system used in flow based cartogram to the coordinates system used in the polygons (characterised by the CRS)

Usage

```
to_coord_polygon(coord, carto)
```

Arguments

coord	a vector of length 2 or a two columns matrix containing xy coordinates to transform
carto	a cartogramR object

Value

a vector of length 2 or a two columns matrix containing xy coordinates in the coordinate systems of polygons used to build the cartogram

Examples

```
data(usa)
carto <- cartogramR(usa, "electors64")
to_coord_polygon(c(256,256), carto)
```

usa	<i>Map of the number of electors in each state of the USA</i>
-----	---

Description

This data set is a basemap of the conterminous USA with the the number of electors in the 49 states from 1964 to 2020.

Usage

```
data(usa)
```

Format

A sf object containing 24 columns of data and the geometry. Projected CRS: US National Atlas Equal Area (EPSG:2163)

warp_features	<i>Apply the deformation used to build a cartogram to a set of simple geometry coordinates</i>
---------------	--

Description

Apply the deformation used to build a cartogram to a set of simple geometry coordinates or simple features. The resulting simple geometry object can be used to add geometry features on the cartogram.

Usage

```
warp_features(sfgeom, carto, verbose = FALSE)
```

Arguments

sfgeom	a sf or a sfc object which contains simple feature geometry of types in the following POINT, MULTIPOINT, LINESTRING, MULTILINESTRING, POLYGON, 'MULTIPOLYGON'
carto	a cartogramR object
verbose	a boolean object to set on verbose mode (default to FALSE)

Value

a sf or a sfc object which contains simple feature geometry transformed

Examples

```
data(usa)
carto <- cartogramR(usa, "electors64")
LA <- sf::st_sfc(sf::st_point(c(-118.243685, 34.052234)))
sf::st_crs(LA) <- 4326
moregeom <- warp_features(LA, carto)
plot(carto)
plot(moregeom, add=TRUE, col=2, pch=15)
```

Index

- * **datasets**
 - france_dept, [9](#)
 - france_rivers, [10](#)
 - usa, [21](#)
- as.sf, [2](#)
- as.sf.cartogramR, [3](#)
- as.sfc, [3](#)
- as.sfc.cartogramR, [4](#)
- as.sfmultipolygon, [4](#)
- cartogramR, [5](#), [6](#), [7](#)
- cartogramR_options, [5](#), [6](#), [6](#), [12](#), [18](#)
- check_ring_dir, [5](#), [8](#), [15](#)
- dist_between_vertices, [9](#), [16](#)
- france_dept, [9](#)
- france_rivers, [10](#)
- from_coord_polygon, [10](#)
- graphics::matplot, [14](#)
- grid_analysis, [11](#), [16](#)
- make_layer, [12](#)
- par, [13](#)
- plot.cartogramR, [12](#)
- plot.dbv.cartogramR, [13](#)
- plot.gridanalysis.cartogramR, [14](#)
- precartogramR, [15](#)
- print.cartogramR, [16](#)
- print.summary.cartogramR, [17](#)
- residuals.cartogramR, [17](#), [19](#)
- sf::st_centroid, [7](#), [12](#)
- sf::st_point_on_surface, [5](#), [7](#), [18](#)
- sf::st_read, [5](#), [15](#)
- summary.cartogramR, [18](#)
- summary.dbv.cartogramR, [19](#)
- summary.gridanalysis.cartogramR, [20](#)
- to_coord_polygon, [21](#)
- usa, [21](#)
- warp_features, [22](#)