Package 'crew.cluster'

November 18, 2024

Title Crew Launcher Plugins for Traditional High-Performance Computing Clusters

Description In computationally demanding analysis projects, statisticians and data scientists asynchronously deploy long-running tasks to distributed systems, ranging from traditional clusters to cloud services. The 'crew.cluster' package extends the 'mirai'-powered 'crew' package with worker launcher plugins for traditional high-performance computing systems. Inspiration also comes from packages 'mirai' by Gao (2023) <https://github.com/shikokuchuo/mirai>, 'future' by Bengtsson (2021) <doi:10.32614/RJ-2021-048>, 'rrq' by FitzJohn and Ashton (2023) <https://github.com/mrc-ide/rrq>, 'clustermq' by Schubert (2019) <doi:10.1093/bioinformatics/btz284>), and 'batchtools' by Lang, Bischl, and Surmann (2017). <doi:10.21105/joss.00135>.

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BugReports https://github.com/wlandau/crew.cluster/issues

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`crew.cluster-package` *crew.cluster: crew launcher plugins for traditional high-performance computing clusters*

Description

In computationally demanding analysis projects, statisticians and data scientists asynchronously deploy long-running tasks to distributed systems, ranging from traditional clusters to cloud services. The `crew.cluster` package extends the `mirai`-powered `crew` package with worker launcher plugins for traditional high-performance computing systems. Inspiration also comes from packages `mirai`, `future`, `rrq`, `clustermq`, and `batchtools`.

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the crew launcher plugins in crew.cluster, and we would like to thank Michael Schubert for developing clustermq and releasing it under the permissive Apache License 2.0. See the NOTICE and README.md files in the crew.cluster source code for additional attribution.

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crew_class_launcher_lsf

[Experimental] *LSF launcher class*

Description

R6 class to launch and manage LSF workers.

Details

See crew_launcher_lsf().

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the crew launcher plugins in crew.cluster, and we would like to thank Michael Schubert for developing clustermq and releasing it under the permissive Apache License 2.0. See the NOTICE and README.md files in the crew.cluster source code for additional attribution.

Super classes

crew::crew_class_launcher -> crew.cluster::crew_class_launcher_cluster -> crew_class_launcher_lsf

Methods

Public methods:

- crew_class_launcher_lsf$validate()
- crew_class_launcher_lsf$script()

Method `validate()`**:** Validate the launcher.

Usage:

```
crew_class_launcher_lsf$validate()
```

Returns: NULL (invisibly). Throws an error if a field is invalid.

Method `script()`**:** Generate the job script.

Usage:

```
crew_class_launcher_lsf$script(name, attempt)
```

Arguments:

`name` Character of length 1, name of the job. For inspection purposes, you can supply a mock job name.

`attempt` Positive integer, number of the current attempt. The attempt number increments each time a worker exits without completing all its tasks, and it resets back to 1 if a worker instance successfully completes all its tasks and then exits normally. By assigning vector arguments to the cluster-specific options of the controller, you can configure different sets of resources for different attempts.

Details: Includes everything except the worker-instance-specific job name and the worker-instance-specific call to `crew::crew_worker()`, both of which get inserted at the bottom of the script at launch time.

Returns: Character vector of the lines of the job script.

Examples:

```
if (identical(Sys.getenv("CREW_EXAMPLES"), "true")) {
launcher <- crew_launcher_lsf(
  lsf_cwd = getwd(),
  lsf_log_output = "log_file_%J.log",
  lsf_log_error = NULL,
  lsf_memory_gigabytes_limit = 4
)
launcher$script(name = "my_job_name")
}
```

See Also

Other lsf: `crew_controller_lsf()`, `crew_launcher_lsf()`, `crew_options_lsf()`

Examples

```
## ------------------------------------------------
## Method `crew_class_launcher_lsf$script`
## ------------------------------------------------

if (identical(Sys.getenv("CREW_EXAMPLES"), "true")) {
launcher <- crew_launcher_lsf(
  lsf_cwd = getwd(),
  lsf_log_output = "log_file_%J.log",
  lsf_log_error = NULL,
  lsf_memory_gigabytes_limit = 4
)
launcher$script(name = "my_job_name")
}
```

crew_class_launcher_pbs

[Maturing] *PBS/TORQUE launcher class*

Description

R6 class to launch and manage PBS/TORQUE workers.

Details

See crew_launcher_pbs().

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the crew launcher plugins in crew.cluster, and we would like to thank Michael Schubert for developing clustermq and releasing it under the permissive Apache License 2.0. See the NOTICE and README.md files in the crew.cluster source code for additional attribution.

Super classes

crew::crew_class_launcher -> crew.cluster::crew_class_launcher_cluster -> crew_class_launcher_pbs

Methods

Public methods:

- crew_class_launcher_pbs$validate()
- crew_class_launcher_pbs$script()

Method validate(): Validate the launcher.

Usage:

```
crew_class_launcher_pbs$validate()
```

Returns: NULL (invisibly). Throws an error if a field is invalid.

Method script(): Generate the job script.

Usage:

```
crew_class_launcher_pbs$script(name, attempt)
```

Arguments:

name Character of length 1, name of the job. For inspection purposes, you can supply a mock job name.

attempt Positive integer, number of the current attempt. The attempt number increments each time a worker exits without completing all its tasks, and it resets back to 1 if a worker instance successfully completes all its tasks and then exits normally. By assigning vector arguments to certain cluster-specific options of the controller, you can configure different sets of resources for different attempts. See cluster-specific option functions like crew_options_slurm() for details.

Details: Includes everything except the worker-instance-specific job name and the worker-instance-specific call to `crew::crew_worker()`, both of which get inserted at the bottom of the script at launch time.

Returns: Character vector of the lines of the job script.

Examples:

```
if (identical(Sys.getenv("CREW_EXAMPLES"), "true")) {
launcher <- crew_launcher_pbs(
  pbs_cores = 2,
  pbs_memory_gigabytes_required = 4
)
launcher$script(name = "my_job_name")
}
```

See Also

Other pbs: `crew_controller_pbs()`, `crew_launcher_pbs()`, `crew_options_pbs()`

Examples

```
## ------------------------------------------------
## Method `crew_class_launcher_pbs$script`
## ------------------------------------------------

if (identical(Sys.getenv("CREW_EXAMPLES"), "true")) {
launcher <- crew_launcher_pbs(
  pbs_cores = 2,
  pbs_memory_gigabytes_required = 4
)
launcher$script(name = "my_job_name")
}
```

`crew_class_launcher_sge`

[Maturing] *SGE launcher class*

Description

`R6` class to launch and manage SGE workers.

Details

See `crew_launcher_sge()`.

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the crew launcher plugins in crew.cluster, and we would like to thank Michael Schubert for developing clustermq and releasing it under the permissive Apache License 2.0. See the NOTICE and README.md files in the crew.cluster source code for additional attribution.

Super classes

crew::crew_class_launcher -> crew.cluster::crew_class_launcher_cluster -> crew_class_launcher_sge

Methods

Public methods:

- crew_class_launcher_sge$validate()
- crew_class_launcher_sge$script()

Method validate(): Validate the launcher.

Usage:

```
crew_class_launcher_sge$validate()
```

Returns: NULL (invisibly). Throws an error if a field is invalid.

Method script(): Generate the job script.

Usage:

```
crew_class_launcher_sge$script(name, attempt)
```

Arguments:

name Character of length 1, name of the job. For inspection purposes, you can supply a mock job name.

attempt Positive integer, number of the current attempt. The attempt number increments each time a worker exits without completing all its tasks, and it resets back to 1 if a worker instance successfully completes all its tasks and then exits normally. By assigning vector arguments to the cluster-specific options of the controller, you can configure different sets of resources for different attempts.

Details: Includes everything except the worker-instance-specific job name and the worker-instance-specific call to crew::crew_worker(), both of which get inserted at the bottom of the script at launch time.

Returns: Character vector of the lines of the job script.

Examples:

```
if (identical(Sys.getenv("CREW_EXAMPLES"), "true")) {
launcher <- crew_launcher_sge(
  sge_cores = 2,
  sge_memory_gigabytes_required = 4
)
launcher$script(name = "my_job_name")
}
```

See Also

Other sge: crew_class_monitor_sge, crew_controller_sge(), crew_launcher_sge(), crew_monitor_sge(), crew_options_sge()

Examples

```
## ------------------------------------------------
## Method `crew_class_launcher_sge$script`
## ------------------------------------------------

if (identical(Sys.getenv("CREW_EXAMPLES"), "true")) {
launcher <- crew_launcher_sge(
  sge_cores = 2,
  sge_memory_gigabytes_required = 4
)
launcher$script(name = "my_job_name")
}
```

---

crew_class_launcher_slurm

[Experimental] *SLURM launcher class*

Description

R6 class to launch and manage SLURM workers.

Details

See crew_launcher_slurm().

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the crew launcher plugins in crew.cluster, and we would like to thank Michael Schubert for developing clustermq and releasing it under the permissive Apache License 2.0. See the NOTICE and README.md files in the crew.cluster source code for additional attribution.

Super classes

crew::crew_class_launcher -> crew.cluster::crew_class_launcher_cluster -> crew_class_launcher_slurm

Methods

Public methods:

- crew_class_launcher_slurm$validate()
- crew_class_launcher_slurm$script()

Method `validate()`**:** Validate the launcher.

Usage:

```
crew_class_launcher_slurm$validate()
```

Returns: `NULL` (invisibly). Throws an error if a field is invalid.

Method `script()`**:** Generate the job script.

Usage:

```
crew_class_launcher_slurm$script(name, attempt)
```

Arguments:

`name` Character of length 1, name of the job. For inspection purposes, you can supply a mock job name.

`attempt` Positive integer, number of the current attempt. The attempt number increments each time a worker exits without completing all its tasks, and it resets back to 1 if a worker instance successfully completes all its tasks and then exits normally. By assigning vector arguments to the cluster-specific options of the controller, you can configure different sets of resources for different attempts.

Details: Includes everything except the worker-instance-specific job name and the worker-instance-specific call to `crew::crew_worker()`, both of which get inserted at the bottom of the script at launch time.

Returns: Character vector of the lines of the job script.

Examples:

```
if (identical(Sys.getenv("CREW_EXAMPLES"), "true")) {
launcher <- crew_launcher_slurm(
  slurm_log_output = "log_file_%A.log",
  slurm_log_error = NULL,
  slurm_memory_gigabytes_per_cpu = 4096
)
launcher$script(name = "my_job_name")
}
```

See Also

Other slurm: `crew_class_monitor_slurm`, `crew_controller_slurm()`, `crew_launcher_slurm()`, `crew_monitor_slurm()`, `crew_options_slurm()`

Examples

```
## ------------------------------------------------
## Method `crew_class_launcher_slurm$script`
## ------------------------------------------------

if (identical(Sys.getenv("CREW_EXAMPLES"), "true")) {
launcher <- crew_launcher_slurm(
  slurm_log_output = "log_file_%A.log",
  slurm_log_error = NULL,
  slurm_memory_gigabytes_per_cpu = 4096
```

```
)
launcher$script(name = "my_job_name")
}
```

`crew_class_monitor_sge` **[Experimental]** *SGE monitor class*

Description

SGE monitor `R6` class

Details

See `crew_monitor_sge()`.

Super class

`crew.cluster::crew_class_monitor_cluster` -> `crew_class_monitor_sge`

Methods

Public methods:

- `crew_class_monitor_sge$jobs()`
- `crew_class_monitor_sge$terminate()`

Method `jobs()`**:** List SGE jobs.

Usage:

```
crew_class_monitor_sge$jobs(user = ps::ps_username())
```

Arguments:

`user` Character of length 1, user name of the jobs to list.

Returns: A `tibble` with one row per SGE job and columns with specific details.

Method `terminate()`**:** Terminate one or more SGE jobs.

Usage:

```
crew_class_monitor_sge$terminate(jobs = NULL, all = FALSE)
```

Arguments:

`jobs` Character vector of job names or job IDs to terminate. Ignored if `all` is set to `TRUE`.

`all` Logical of length 1, whether to terminate all the jobs under your user name. This terminates ALL your SGE jobs, regardless of whether `crew.cluster` launched them, so use with caution!

Returns: `NULL` (invisibly).

See Also

Other sge: `crew_class_launcher_sge`, `crew_controller_sge()`, `crew_launcher_sge()`, `crew_monitor_sge()`, `crew_options_sge()`

crew_class_monitor_slurm **[Experimental]** *SLURM monitor class*

Description

SLURM monitor R6 class

Details

See crew_monitor_slurm().

Super class

crew.cluster::crew_class_monitor_cluster -> crew_class_monitor_slurm

Methods

Public methods:

- crew_class_monitor_slurm$jobs()
- crew_class_monitor_slurm$terminate()

Method jobs(): List SLURM jobs.

Usage:

```
crew_class_monitor_slurm$jobs(user = ps::ps_username())
```

Arguments:

user Character of length 1, user name of the jobs to list.

Details: This function loads the entire SLURM queue for all users, so it may take several seconds to execute. It is intended for interactive use, and should especially be avoided in scripts where it is called frequently. It requires SLURM version 20.02 or higher, along with the YAML plugin.

Returns: A tibble with one row per SLURM job and columns with specific details.

Method terminate(): Terminate one or more SLURM jobs.

Usage:

```
crew_class_monitor_slurm$terminate(jobs = NULL, all = FALSE)
```

Arguments:

jobs Character vector of job names or job IDs to terminate. Ignored if all is set to TRUE.

all Logical of length 1, whether to terminate all the jobs under your user name. This terminates ALL your SLURM jobs, regardless of whether crew.cluster launched them, so use with caution!

Returns: NULL (invisibly).

See Also

Other slurm: crew_class_launcher_slurm, crew_controller_slurm(), crew_launcher_slurm(), crew_monitor_slurm(), crew_options_slurm()

`crew_controller_lsf` **[Experimental]** *Create a controller with a LSF launcher.*

Description

Create an R6 object to submit tasks and launch workers on LSF workers.

Usage

```
crew_controller_lsf(
  name = NULL,
  workers = 1L,
  host = NULL,
  port = NULL,
  tls = crew::crew_tls(mode = "automatic"),
  tls_enable = NULL,
  tls_config = NULL,
  seconds_interval = 0.25,
  seconds_timeout = 60,
  seconds_launch = 86400,
  seconds_idle = 300,
  seconds_wall = Inf,
  seconds_exit = NULL,
  retry_tasks = TRUE,
  tasks_max = Inf,
  tasks_timers = 0L,
  reset_globals = TRUE,
  reset_packages = FALSE,
  reset_options = FALSE,
  garbage_collection = FALSE,
  crashes_error = 5L,
  r_arguments = c("--no-save", "--no-restore"),
  options_metrics = crew::crew_options_metrics(),
  options_cluster = crew.cluster::crew_options_lsf(),
  verbose = NULL,
  command_submit = NULL,
  command_terminate = NULL,
  command_delete = NULL,
  script_directory = NULL,
  script_lines = NULL,
  lsf_cwd = NULL,
  lsf_log_output = NULL,
```

```
  lsf_log_error = NULL,
  lsf_memory_gigabytes_limit = NULL,
  lsf_memory_gigabytes_required = NULL,
  lsf_cores = NULL
)
```

Arguments

name	Name of the client object. If NULL, a name is automatically generated.
workers	Integer, maximum number of parallel workers to run.
host	IP address of the mirai client to send and receive tasks. If NULL, the host defaults to the local IP address.
port	TCP port to listen for the workers. If NULL, then an available ephemeral port is automatically chosen.
tls	A TLS configuration object from crew_tls().
tls_enable	Deprecated on 2023-09-15 in version 0.4.1. Use argument tls instead.
tls_config	Deprecated on 2023-09-15 in version 0.4.1. Use argument tls instead.
seconds_interval	Number of seconds between polling intervals waiting for certain internal synchronous operations to complete, such as checking mirai::status()
seconds_timeout	Number of seconds until timing out while waiting for certain synchronous operations to complete, such as checking mirai::status().
seconds_launch	Seconds of startup time to allow. A worker is unconditionally assumed to be alive from the moment of its launch until seconds_launch seconds later. After seconds_launch seconds, the worker is only considered alive if it is actively connected to its assign websocket.
seconds_idle	Maximum number of seconds that a worker can idle since the completion of the last task. If exceeded, the worker exits. But the timer does not launch until tasks_timers tasks have completed. See the idletime argument of mirai::daemon(). crew does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, so please allow enough idle time for a new worker to be delegated a new task.
seconds_wall	Soft wall time in seconds. The timer does not launch until tasks_timers tasks have completed. See the walltime argument of mirai::daemon().
seconds_exit	Deprecated on 2023-09-21 in version 0.1.2.9000. No longer necessary.
retry_tasks	TRUE to automatically retry a task in the event of an unexpected worker exit. FALSE to give up on the first exit and return a mirai error code (code number 19). TRUE (default) is recommended in most situations. Use FALSE for debugging purposes, e.g. to confirm that a task is causing a worker to run out of memory or crash in some other way.
tasks_max	Maximum number of tasks that a worker will do before exiting. See the maxtasks argument of mirai::daemon(). crew does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, it is recommended to set tasks_max to a value greater than 1.

`tasks_timers` Number of tasks to do before activating the timers for `seconds_idle` and `seconds_wall`. See the `timerstart` argument of `mirai::daemon()`.

`reset_globals` `TRUE` to reset global environment variables between tasks, `FALSE` to leave them alone.

`reset_packages` `TRUE` to unload any packages loaded during a task (runs between each task), `FALSE` to leave packages alone.

`reset_options` `TRUE` to reset global options to their original state between each task, `FALSE` otherwise. It is recommended to only set `reset_options = TRUE` if `reset_packages` is also `TRUE` because packages sometimes rely on options they set at loading time.

`garbage_collection`
`TRUE` to run garbage collection between tasks, `FALSE` to skip.

`crashes_error` Positive integer scalar. If a worker exits `crashes_error` times in a row without completing all its assigned tasks, then the launcher throws an informative error. The reason for `crashes_error` is to avoid an infinite loop where a task crashes a worker (through a segfault, maxing out memory, etc) but the worker always relaunches. To monitor the resources of `crew` workers, please see https://wlandau.github.io/crew/articles/logging.html.

`r_arguments` Optional character vector of command line arguments to pass to `Rscript` (non-Windows) or `Rscript.exe` (Windows) when starting a worker. Example: `r_arguments = c("--vanilla", "--max-connections=32")`.

`options_metrics`
Either `NULL` to opt out of resource metric logging for workers, or an object from `crew_options_metrics()` to enable and configure resource metric logging for workers. For resource logging to run, the `autometric` R package version 0.1.0 or higher must be installed.

`options_cluster`
An options list from `crew_options_lsf()` with cluster-specific configuration options.

`verbose` Deprecated. Use `options_cluster` instead.

`command_submit` Deprecated. Use `options_cluster` instead.

`command_terminate`
Deprecated. Use `options_cluster` instead.

`command_delete` Deprecated on 2024-01-08 (version 0.1.4.9001). Use `command_terminate` instead.

`script_directory`
Deprecated. Use `options_cluster` instead.

`script_lines` Deprecated. Use `options_cluster` instead.

`lsf_cwd` Deprecated. Use `options_cluster` instead.

`lsf_log_output` Deprecated. Use `options_cluster` instead.

`lsf_log_error` Deprecated. Use `options_cluster` instead.

`lsf_memory_gigabytes_limit`
Deprecated. Use `options_cluster` instead.

`lsf_memory_gigabytes_required`
Deprecated. Use `options_cluster` instead.

`lsf_cores` Deprecated. Use `options_cluster` instead.

Details

WARNING: the crew.cluster LSF plugin is experimental and has not actually been tested on a LSF cluster. Please proceed with caution and report bugs to https://github.com/wlandau/crew.cluster.

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the crew launcher plugins in crew.cluster, and we would like to thank Michael Schubert for developing clustermq and releasing it under the permissive Apache License 2.0. See the NOTICE and README.md files in the crew.cluster source code for additional attribution.

See Also

Other lsf: crew_class_launcher_lsf, crew_launcher_lsf(), crew_options_lsf()

Examples

```
if (identical(Sys.getenv("CREW_EXAMPLES"), "true")) {
controller <- crew_controller_lsf()
controller$start()
controller$push(name = "task", command = sqrt(4))
controller$wait()
controller$pop()$result
controller$terminate()
}
```

---

crew_controller_pbs **[Experimental]** *Create a controller with a PBS/TORQUE launcher.*

Description

Create an R6 object to submit tasks and launch workers on a PBS or TORQUE cluster.

Usage

```
crew_controller_pbs(
  name = NULL,
  workers = 1L,
  host = NULL,
  port = NULL,
  tls = crew::crew_tls(mode = "automatic"),
  tls_enable = NULL,
  tls_config = NULL,
  seconds_interval = 0.25,
  seconds_timeout = 60,
  seconds_launch = 86400,
```

```
  seconds_idle = 300,
  seconds_wall = Inf,
  seconds_exit = NULL,
  retry_tasks = TRUE,
  tasks_max = Inf,
  tasks_timers = 0L,
  reset_globals = TRUE,
  reset_packages = FALSE,
  reset_options = FALSE,
  garbage_collection = FALSE,
  crashes_error = 5L,
  r_arguments = c("--no-save", "--no-restore"),
  options_metrics = crew::crew_options_metrics(),
  options_cluster = crew.cluster::crew_options_pbs(),
  verbose = NULL,
  command_submit = NULL,
  command_terminate = NULL,
  command_delete = NULL,
  script_directory = NULL,
  script_lines = NULL,
  pbs_cwd = NULL,
  pbs_log_output = NULL,
  pbs_log_error = NULL,
  pbs_log_join = NULL,
  pbs_memory_gigabytes_required = NULL,
  pbs_cores = NULL,
  pbs_walltime_hours = NULL
)
```

Arguments

`name`	Name of the client object. If `NULL`, a name is automatically generated.
`workers`	Integer, maximum number of parallel workers to run.
`host`	IP address of the `mirai` client to send and receive tasks. If `NULL`, the host defaults to the local IP address.
`port`	TCP port to listen for the workers. If `NULL`, then an available ephemeral port is automatically chosen.
`tls`	A TLS configuration object from `crew_tls()`.
`tls_enable`	Deprecated on 2023-09-15 in version 0.4.1. Use argument `tls` instead.
`tls_config`	Deprecated on 2023-09-15 in version 0.4.1. Use argument `tls` instead.
`seconds_interval`	Number of seconds between polling intervals waiting for certain internal synchronous operations to complete, such as checking `mirai::status()`
`seconds_timeout`	Number of seconds until timing out while waiting for certain synchronous operations to complete, such as checking `mirai::status()`.

seconds_launch
: Seconds of startup time to allow. A worker is unconditionally assumed to be alive from the moment of its launch until seconds_launch seconds later. After seconds_launch seconds, the worker is only considered alive if it is actively connected to its assign websocket.

seconds_idle
: Maximum number of seconds that a worker can idle since the completion of the last task. If exceeded, the worker exits. But the timer does not launch until tasks_timers tasks have completed. See the idletime argument of mirai::daemon(). crew does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, so please allow enough idle time for a new worker to be delegated a new task.

seconds_wall
: Soft wall time in seconds. The timer does not launch until tasks_timers tasks have completed. See the walltime argument of mirai::daemon().

seconds_exit
: Deprecated on 2023-09-21 in version 0.1.2.9000. No longer necessary.

retry_tasks
: TRUE to automatically retry a task in the event of an unexpected worker exit. FALSE to give up on the first exit and return a mirai error code (code number 19). TRUE (default) is recommended in most situations. Use FALSE for debugging purposes, e.g. to confirm that a task is causing a worker to run out of memory or crash in some other way.

tasks_max
: Maximum number of tasks that a worker will do before exiting. See the maxtasks argument of mirai::daemon(). crew does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, it is recommended to set tasks_max to a value greater than 1.

tasks_timers
: Number of tasks to do before activating the timers for seconds_idle and seconds_wall. See the timerstart argument of mirai::daemon().

reset_globals
: TRUE to reset global environment variables between tasks, FALSE to leave them alone.

reset_packages
: TRUE to unload any packages loaded during a task (runs between each task), FALSE to leave packages alone.

reset_options
: TRUE to reset global options to their original state between each task, FALSE otherwise. It is recommended to only set reset_options = TRUE if reset_packages is also TRUE because packages sometimes rely on options they set at loading time.

garbage_collection
: TRUE to run garbage collection between tasks, FALSE to skip.

crashes_error
: Positive integer scalar. If a worker exits crashes_error times in a row without completing all its assigned tasks, then the launcher throws an informative error. The reason for crashes_error is to avoid an infinite loop where a task crashes a worker (through a segfault, maxing out memory, etc) but the worker always relaunches. To monitor the resources of crew workers, please see https://wlandau.github.io/crew/articles/logging.html.

r_arguments
: Optional character vector of command line arguments to pass to Rscript (non-Windows) or Rscript.exe (Windows) when starting a worker. Example: r_arguments = c("--vanilla", "--max-connections=32").

options_metrics
: Either NULL to opt out of resource metric logging for workers, or an object from crew_options_metrics() to enable and configure resource metric logging for

workers. For resource logging to run, the `autometric` R package version 0.1.0 or higher must be installed.

`options_cluster`
: An options list from `crew_options_pbs()` with cluster-specific configuration options.

`verbose`
: Deprecated. Use `options_cluster` instead.

`command_submit`
: Deprecated. Use `options_cluster` instead.

`command_terminate`
: Deprecated. Use `options_cluster` instead.

`command_delete`
: Deprecated on 2024-01-08 (version 0.1.4.9001). Use `command_terminate` instead.

`script_directory`
: Deprecated. Use `options_cluster` instead.

`script_lines`
: Deprecated. Use `options_cluster` instead.

`pbs_cwd`
: Deprecated. Use `options_cluster` instead.

`pbs_log_output`
: Deprecated. Use `options_cluster` instead.

`pbs_log_error`
: Deprecated. Use `options_cluster` instead.

`pbs_log_join`
: Deprecated. Use `options_cluster` instead.

`pbs_memory_gigabytes_required`
: Deprecated. Use `options_cluster` instead.

`pbs_cores`
: Deprecated. Use `options_cluster` instead.

`pbs_walltime_hours`
: Deprecated. Use `options_cluster` instead.

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the `crew` launcher plugins in `crew.cluster`, and we would like to thank Michael Schubert for developing `clustermq` and releasing it under the permissive Apache License 2.0. See the `NOTICE` and `README.md` files in the `crew.cluster` source code for additional attribution.

See Also

Other pbs: `crew_class_launcher_pbs`, `crew_launcher_pbs()`, `crew_options_pbs()`

Examples

```
if (identical(Sys.getenv("CREW_EXAMPLES"), "true")) {
controller <- crew_controller_pbs()
controller$start()
controller$push(name = "task", command = sqrt(4))
controller$wait()
controller$pop()$result
controller$terminate()
}
```

crew_controller_sge **[Maturing]** *Create a controller with a Sun Grid Engine (SGE) launcher.*

Description

Create an R6 object to submit tasks and launch workers on Sun Grid Engine (SGE) workers.

Usage

```
crew_controller_sge(
  name = NULL,
  workers = 1L,
  host = NULL,
  port = NULL,
  tls = crew::crew_tls(mode = "automatic"),
  tls_enable = NULL,
  tls_config = NULL,
  seconds_interval = 0.25,
  seconds_timeout = 60,
  seconds_launch = 86400,
  seconds_idle = 300,
  seconds_wall = Inf,
  seconds_exit = NULL,
  retry_tasks = TRUE,
  tasks_max = Inf,
  tasks_timers = 0L,
  reset_globals = TRUE,
  reset_packages = FALSE,
  reset_options = FALSE,
  garbage_collection = FALSE,
  crashes_error = 5L,
  r_arguments = c("--no-save", "--no-restore"),
  options_metrics = crew::crew_options_metrics(),
  options_cluster = crew.cluster::crew_options_sge(),
  verbose = NULL,
  command_submit = NULL,
  command_terminate = NULL,
  command_delete = NULL,
  script_directory = NULL,
  script_lines = NULL,
  sge_cwd = NULL,
  sge_envvars = NULL,
  sge_log_output = NULL,
  sge_log_error = NULL,
  sge_log_join = NULL,
  sge_memory_gigabytes_limit = NULL,
```

```
  sge_memory_gigabytes_required = NULL,
  sge_cores = NULL,
  sge_gpu = NULL
)
```

Arguments

name	Name of the client object. If NULL, a name is automatically generated.
workers	Integer, maximum number of parallel workers to run.
host	IP address of the mirai client to send and receive tasks. If NULL, the host defaults to the local IP address.
port	TCP port to listen for the workers. If NULL, then an available ephemeral port is automatically chosen.
tls	A TLS configuration object from crew_tls().
tls_enable	Deprecated on 2023-09-15 in version 0.4.1. Use argument tls instead.
tls_config	Deprecated on 2023-09-15 in version 0.4.1. Use argument tls instead.
seconds_interval	Number of seconds between polling intervals waiting for certain internal synchronous operations to complete, such as checking mirai::status()
seconds_timeout	Number of seconds until timing out while waiting for certain synchronous operations to complete, such as checking mirai::status().
seconds_launch	Seconds of startup time to allow. A worker is unconditionally assumed to be alive from the moment of its launch until seconds_launch seconds later. After seconds_launch seconds, the worker is only considered alive if it is actively connected to its assign websocket.
seconds_idle	Maximum number of seconds that a worker can idle since the completion of the last task. If exceeded, the worker exits. But the timer does not launch until tasks_timers tasks have completed. See the idletime argument of mirai::daemon(). crew does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, so please allow enough idle time for a new worker to be delegated a new task.
seconds_wall	Soft wall time in seconds. The timer does not launch until tasks_timers tasks have completed. See the walltime argument of mirai::daemon().
seconds_exit	Deprecated on 2023-09-21 in version 0.1.2.9000. No longer necessary.
retry_tasks	TRUE to automatically retry a task in the event of an unexpected worker exit. FALSE to give up on the first exit and return a mirai error code (code number 19). TRUE (default) is recommended in most situations. Use FALSE for debugging purposes, e.g. to confirm that a task is causing a worker to run out of memory or crash in some other way.
tasks_max	Maximum number of tasks that a worker will do before exiting. See the maxtasks argument of mirai::daemon(). crew does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, it is recommended to set tasks_max to a value greater than 1.

`tasks_timers` Number of tasks to do before activating the timers for `seconds_idle` and `seconds_wall`. See the `timerstart` argument of `mirai::daemon()`.

`reset_globals` `TRUE` to reset global environment variables between tasks, `FALSE` to leave them alone.

`reset_packages` `TRUE` to unload any packages loaded during a task (runs between each task), `FALSE` to leave packages alone.

`reset_options` `TRUE` to reset global options to their original state between each task, `FALSE` otherwise. It is recommended to only set `reset_options = TRUE` if `reset_packages` is also `TRUE` because packages sometimes rely on options they set at loading time.

`garbage_collection`
`TRUE` to run garbage collection between tasks, `FALSE` to skip.

`crashes_error` Positive integer scalar. If a worker exits `crashes_error` times in a row without completing all its assigned tasks, then the launcher throws an informative error. The reason for `crashes_error` is to avoid an infinite loop where a task crashes a worker (through a segfault, maxing out memory, etc) but the worker always relaunches. To monitor the resources of `crew` workers, please see https://wlandau.github.io/crew/articles/logging.html.

`r_arguments` Optional character vector of command line arguments to pass to `Rscript` (non-Windows) or `Rscript.exe` (Windows) when starting a worker. Example: `r_arguments = c("--vanilla", "--max-connections=32")`.

`options_metrics`
Either `NULL` to opt out of resource metric logging for workers, or an object from `crew_options_metrics()` to enable and configure resource metric logging for workers. For resource logging to run, the `autometric` R package version 0.1.0 or higher must be installed.

`options_cluster`
An options list from `crew_options_sge()` with cluster-specific configuration options.

`verbose` Deprecated. Use `options_cluster` instead.

`command_submit` Deprecated. Use `options_cluster` instead.

`command_terminate`
Deprecated. Use `options_cluster` instead.

`command_delete` Deprecated on 2024-01-08 (version 0.1.4.9001). Use `command_terminate` instead.

`script_directory`
Deprecated. Use `options_cluster` instead.

`script_lines` Deprecated. Use `options_cluster` instead.

`sge_cwd` Deprecated. Use `options_cluster` instead.

`sge_envvars` Deprecated. Use `options_cluster` instead.

`sge_log_output` Deprecated. Use `options_cluster` instead.

`sge_log_error` Deprecated. Use `options_cluster` instead.

`sge_log_join` Deprecated. Use `options_cluster` instead.

`sge_memory_gigabytes_limit`
: Deprecated. Use `options_cluster` instead.

`sge_memory_gigabytes_required`
: Deprecated. Use `options_cluster` instead.

`sge_cores`
: Deprecated. Use `options_cluster` instead.

`sge_gpu`
: Deprecated. Use `options_cluster` instead.

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the `crew` launcher plugins in `crew.cluster`, and we would like to thank Michael Schubert for developing `clustermq` and releasing it under the permissive Apache License 2.0. See the `NOTICE` and `README.md` files in the `crew.cluster` source code for additional attribution.

See Also

Other sge: `crew_class_launcher_sge`, `crew_class_monitor_sge`, `crew_launcher_sge()`, `crew_monitor_sge()`, `crew_options_sge()`

Examples

```
if (identical(Sys.getenv("CREW_EXAMPLES"), "true")) {
controller <- crew_controller_sge()
controller$start()
controller$push(name = "task", command = sqrt(4))
controller$wait()
controller$pop()$result
controller$terminate()
}
```

`crew_controller_slurm` **[Experimental]** *Create a controller with a SLURM launcher.*

Description

Create an `R6` object to submit tasks and launch workers on SLURM workers.

Usage

```
crew_controller_slurm(
  name = NULL,
  workers = 1L,
  host = NULL,
  port = NULL,
  tls = crew::crew_tls(mode = "automatic"),
  tls_enable = NULL,
  tls_config = NULL,
```

```
  seconds_interval = 0.25,
  seconds_timeout = 60,
  seconds_launch = 86400,
  seconds_idle = 300,
  seconds_wall = Inf,
  seconds_exit = NULL,
  retry_tasks = TRUE,
  tasks_max = Inf,
  tasks_timers = 0L,
  reset_globals = TRUE,
  reset_packages = FALSE,
  reset_options = FALSE,
  garbage_collection = FALSE,
  crashes_error = 5L,
  r_arguments = c("--no-save", "--no-restore"),
  options_metrics = crew::crew_options_metrics(),
  options_cluster = crew.cluster::crew_options_slurm(),
  verbose = NULL,
  command_submit = NULL,
  command_terminate = NULL,
  command_delete = NULL,
  script_directory = NULL,
  script_lines = NULL,
  slurm_log_output = NULL,
  slurm_log_error = NULL,
  slurm_memory_gigabytes_required = NULL,
  slurm_memory_gigabytes_per_cpu = NULL,
  slurm_cpus_per_task = NULL,
  slurm_time_minutes = NULL,
  slurm_partition = NULL
)
```

Arguments

`name`	Name of the client object. If `NULL`, a name is automatically generated.
`workers`	Integer, maximum number of parallel workers to run.
`host`	IP address of the `mirai` client to send and receive tasks. If `NULL`, the host defaults to the local IP address.
`port`	TCP port to listen for the workers. If `NULL`, then an available ephemeral port is automatically chosen.
`tls`	A TLS configuration object from `crew_tls()`.
`tls_enable`	Deprecated on 2023-09-15 in version 0.4.1. Use argument `tls` instead.
`tls_config`	Deprecated on 2023-09-15 in version 0.4.1. Use argument `tls` instead.
`seconds_interval`	Number of seconds between polling intervals waiting for certain internal synchronous operations to complete, such as checking `mirai::status()`

seconds_timeout
: Number of seconds until timing out while waiting for certain synchronous operations to complete, such as checking `mirai::status()`.

seconds_launch
: Seconds of startup time to allow. A worker is unconditionally assumed to be alive from the moment of its launch until `seconds_launch` seconds later. After `seconds_launch` seconds, the worker is only considered alive if it is actively connected to its assign websocket.

seconds_idle
: Maximum number of seconds that a worker can idle since the completion of the last task. If exceeded, the worker exits. But the timer does not launch until `tasks_timers` tasks have completed. See the `idletime` argument of `mirai::daemon()`. `crew` does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, so please allow enough idle time for a new worker to be delegated a new task.

seconds_wall
: Soft wall time in seconds. The timer does not launch until `tasks_timers` tasks have completed. See the `walltime` argument of `mirai::daemon()`.

seconds_exit
: Deprecated on 2023-09-21 in version 0.1.2.9000. No longer necessary.

retry_tasks
: `TRUE` to automatically retry a task in the event of an unexpected worker exit. `FALSE` to give up on the first exit and return a `mirai` error code (code number 19). `TRUE` (default) is recommended in most situations. Use `FALSE` for debugging purposes, e.g. to confirm that a task is causing a worker to run out of memory or crash in some other way.

tasks_max
: Maximum number of tasks that a worker will do before exiting. See the `maxtasks` argument of `mirai::daemon()`. `crew` does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, it is recommended to set `tasks_max` to a value greater than 1.

tasks_timers
: Number of tasks to do before activating the timers for `seconds_idle` and `seconds_wall`. See the `timerstart` argument of `mirai::daemon()`.

reset_globals
: `TRUE` to reset global environment variables between tasks, `FALSE` to leave them alone.

reset_packages
: `TRUE` to unload any packages loaded during a task (runs between each task), `FALSE` to leave packages alone.

reset_options
: `TRUE` to reset global options to their original state between each task, `FALSE` otherwise. It is recommended to only set `reset_options = TRUE` if `reset_packages` is also `TRUE` because packages sometimes rely on options they set at loading time.

garbage_collection
: `TRUE` to run garbage collection between tasks, `FALSE` to skip.

crashes_error
: Positive integer scalar. If a worker exits `crashes_error` times in a row without completing all its assigned tasks, then the launcher throws an informative error. The reason for `crashes_error` is to avoid an infinite loop where a task crashes a worker (through a segfault, maxing out memory, etc) but the worker always relaunches. To monitor the resources of `crew` workers, please see https://wlandau.github.io/crew/articles/logging.html.

r_arguments
: Optional character vector of command line arguments to pass to `Rscript` (non-Windows) or `Rscript.exe` (Windows) when starting a worker. Example: `r_arguments = c("--vanilla", "--max-connections=32")`.

`options_metrics`
: Either `NULL` to opt out of resource metric logging for workers, or an object from `crew_options_metrics()` to enable and configure resource metric logging for workers. For resource logging to run, the `autometric` R package version 0.1.0 or higher must be installed.

`options_cluster`
: An options list from `crew_options_slurm()` with cluster-specific configuration options.

`verbose`
: Deprecated. Use `options_cluster` instead.

`command_submit`
: Deprecated. Use `options_cluster` instead.

`command_terminate`
: Deprecated. Use `options_cluster` instead.

`command_delete`
: Deprecated on 2024-01-08 (version 0.1.4.9001). Use `command_terminate` instead.

`script_directory`
: Deprecated. Use `options_cluster` instead.

`script_lines`
: Deprecated. Use `options_cluster` instead.

`slurm_log_output`
: Deprecated. Use `options_cluster` instead.

`slurm_log_error`
: Deprecated. Use `options_cluster` instead.

`slurm_memory_gigabytes_required`
: Deprecated. Use `options_cluster` instead.

`slurm_memory_gigabytes_per_cpu`
: Deprecated. Use `options_cluster` instead.

`slurm_cpus_per_task`
: Deprecated. Use `options_cluster` instead.

`slurm_time_minutes`
: Deprecated. Use `options_cluster` instead.

`slurm_partition`
: Deprecated. Use `options_cluster` instead.

Details

WARNING: the `crew.cluster` SLURM plugin is experimental and has not actually been tested on a SLURM cluster. Please proceed with caution and report bugs to https://github.com/wlandau/crew.cluster.

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the `crew` launcher plugins in `crew.cluster`, and we would like to thank Michael Schubert for developing `clustermq` and releasing it under the permissive Apache License 2.0. See the `NOTICE` and `README.md` files in the `crew.cluster` source code for additional attribution.

See Also

Other slurm: crew_class_launcher_slurm, crew_class_monitor_slurm, crew_launcher_slurm(), crew_monitor_slurm(), crew_options_slurm()

Examples

```
if (identical(Sys.getenv("CREW_EXAMPLES"), "true")) {
controller <- crew_controller_slurm()
controller$start()
controller$push(name = "task", command = sqrt(4))
controller$wait()
controller$pop()$result
controller$terminate()
}
```

---

crew_launcher_lsf **[Experimental]** *Create a launcher with LSF workers.*

Description

Create an R6 object to launch and maintain workers as LSF jobs.

Usage

```
crew_launcher_lsf(
  name = NULL,
  seconds_interval = 0.5,
  seconds_timeout = 60,
  seconds_launch = 86400,
  seconds_idle = 300,
  seconds_wall = Inf,
  tasks_max = Inf,
  tasks_timers = 0L,
  reset_globals = TRUE,
  reset_packages = FALSE,
  reset_options = FALSE,
  garbage_collection = FALSE,
  crashes_error = 5L,
  tls = crew::crew_tls(mode = "automatic"),
  r_arguments = c("--no-save", "--no-restore"),
  options_metrics = crew::crew_options_metrics(),
  options_cluster = crew.cluster::crew_options_lsf(),
  verbose = NULL,
  command_submit = NULL,
  command_terminate = NULL,
  command_delete = NULL,
  script_directory = NULL,
```

```
  script_lines = NULL,
  lsf_cwd = NULL,
  lsf_log_output = NULL,
  lsf_log_error = NULL,
  lsf_memory_gigabytes_limit = NULL,
  lsf_memory_gigabytes_required = NULL,
  lsf_cores = NULL
)
```

Arguments

name	Name of the launcher.
seconds_interval	Number of seconds between polling intervals waiting for certain internal synchronous operations to complete, such as checking `mirai::status()`.
seconds_timeout	Number of seconds until timing out while waiting for certain synchronous operations to complete, such as checking `mirai::status()`.
seconds_launch	Seconds of startup time to allow. A worker is unconditionally assumed to be alive from the moment of its launch until `seconds_launch` seconds later. After `seconds_launch` seconds, the worker is only considered alive if it is actively connected to its assign websocket.
seconds_idle	Maximum number of seconds that a worker can idle since the completion of the last task. If exceeded, the worker exits. But the timer does not launch until `tasks_timers` tasks have completed. See the `idletime` argument of `mirai::daemon()`. `crew` does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, so please allow enough idle time for a new worker to be delegated a new task.
seconds_wall	Soft wall time in seconds. The timer does not launch until `tasks_timers` tasks have completed. See the `walltime` argument of `mirai::daemon()`.
tasks_max	Maximum number of tasks that a worker will do before exiting. See the `maxtasks` argument of `mirai::daemon()`. `crew` does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, it is recommended to set `tasks_max` to a value greater than 1.
tasks_timers	Number of tasks to do before activating the timers for `seconds_idle` and `seconds_wall`. See the `timerstart` argument of `mirai::daemon()`.
reset_globals	`TRUE` to reset global environment variables between tasks, `FALSE` to leave them alone.
reset_packages	`TRUE` to unload any packages loaded during a task (runs between each task), `FALSE` to leave packages alone.
reset_options	`TRUE` to reset global options to their original state between each task, `FALSE` otherwise. It is recommended to only set `reset_options = TRUE` if `reset_packages` is also `TRUE` because packages sometimes rely on options they set at loading time.
garbage_collection	`TRUE` to run garbage collection between tasks, `FALSE` to skip.

`crashes_error` Positive integer scalar. If a worker exits `crashes_error` times in a row without completing all its assigned tasks, then the launcher throws an informative error. The reason for `crashes_error` is to avoid an infinite loop where a task crashes a worker (through a segfault, maxing out memory, etc) but the worker always relaunches. To monitor the resources of `crew` workers, please see https://wlandau.github.io/crew/articles/logging.html.

`tls` A TLS configuration object from `crew_tls()`.

`r_arguments` Optional character vector of command line arguments to pass to `Rscript` (non-Windows) or `Rscript.exe` (Windows) when starting a worker. Example: `r_arguments = c("--vanilla", "--max-connections=32")`.

`options_metrics`
Either `NULL` to opt out of resource metric logging for workers, or an object from `crew_options_metrics()` to enable and configure resource metric logging for workers. For resource logging to run, the `autometric` R package version 0.1.0 or higher must be installed.

`options_cluster`
An options list from `crew_options_lsf()` with cluster-specific configuration options.

`verbose` Deprecated. Use `options_cluster` instead.

`command_submit` Deprecated. Use `options_cluster` instead.

`command_terminate`
Deprecated. Use `options_cluster` instead.

`command_delete` Deprecated on 2024-01-08 (version 0.1.4.9001). Use `command_terminate` instead.

`script_directory`
Deprecated. Use `options_cluster` instead.

`script_lines` Deprecated. Use `options_cluster` instead.

`lsf_cwd` Deprecated. Use `options_cluster` instead.

`lsf_log_output` Deprecated. Use `options_cluster` instead.

`lsf_log_error` Deprecated. Use `options_cluster` instead.

`lsf_memory_gigabytes_limit`
Deprecated. Use `options_cluster` instead.

`lsf_memory_gigabytes_required`
Deprecated. Use `options_cluster` instead.

`lsf_cores` Deprecated. Use `options_cluster` instead.

Details

WARNING: the `crew.cluster` LSF plugin is experimental. Please proceed with caution and report bugs to https://github.com/wlandau/crew.cluster.

To launch a LSF worker, this launcher creates a temporary job script with a call to `crew::crew_worker()` and submits it as an LSF job with `sbatch`. To see most of the lines of the job script in advance, use the `script()` method of the launcher. It has all the lines except for the job name and the call to `crew::crew_worker()`, both of which will be inserted at the last minute when it is time to actually launch a worker.

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the crew launcher plugins in crew.cluster, and we would like to thank Michael Schubert for developing clustermq and releasing it under the permissive Apache License 2.0. See the NOTICE and README.md files in the crew.cluster source code for additional attribution.

See Also

Other lsf: crew_class_launcher_lsf, crew_controller_lsf(), crew_options_lsf()

---

crew_launcher_pbs **[Experimental]** *Create a launcher with PBS or TORQUE workers.*

Description

Create an R6 object to launch and maintain workers as jobs on a PBS or TORQUE cluster.

Usage

```
crew_launcher_pbs(
  name = NULL,
  seconds_interval = 0.5,
  seconds_timeout = 60,
  seconds_launch = 86400,
  seconds_idle = 300,
  seconds_wall = Inf,
  tasks_max = Inf,
  tasks_timers = 0L,
  reset_globals = TRUE,
  reset_packages = FALSE,
  reset_options = FALSE,
  garbage_collection = FALSE,
  crashes_error = 5L,
  tls = crew::crew_tls(mode = "automatic"),
  r_arguments = c("--no-save", "--no-restore"),
  options_metrics = crew::crew_options_metrics(),
  options_cluster = crew.cluster::crew_options_pbs(),
  verbose = NULL,
  command_submit = NULL,
  command_terminate = NULL,
  command_delete = NULL,
  script_directory = NULL,
  script_lines = NULL,
  pbs_cwd = NULL,
  pbs_log_output = NULL,
  pbs_log_error = NULL,
```

```
  pbs_log_join = NULL,
  pbs_memory_gigabytes_required = NULL,
  pbs_cores = NULL,
  pbs_walltime_hours = NULL
)
```

Arguments

name	Name of the launcher.
seconds_interval	Number of seconds between polling intervals waiting for certain internal synchronous operations to complete, such as checking `mirai::status()`.
seconds_timeout	Number of seconds until timing out while waiting for certain synchronous operations to complete, such as checking `mirai::status()`.
seconds_launch	Seconds of startup time to allow. A worker is unconditionally assumed to be alive from the moment of its launch until `seconds_launch` seconds later. After `seconds_launch` seconds, the worker is only considered alive if it is actively connected to its assign websocket.
seconds_idle	Maximum number of seconds that a worker can idle since the completion of the last task. If exceeded, the worker exits. But the timer does not launch until `tasks_timers` tasks have completed. See the `idletime` argument of `mirai::daemon()`. `crew` does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, so please allow enough idle time for a new worker to be delegated a new task.
seconds_wall	Soft wall time in seconds. The timer does not launch until `tasks_timers` tasks have completed. See the `walltime` argument of `mirai::daemon()`.
tasks_max	Maximum number of tasks that a worker will do before exiting. See the `maxtasks` argument of `mirai::daemon()`. `crew` does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, it is recommended to set `tasks_max` to a value greater than 1.
tasks_timers	Number of tasks to do before activating the timers for `seconds_idle` and `seconds_wall`. See the `timerstart` argument of `mirai::daemon()`.
reset_globals	`TRUE` to reset global environment variables between tasks, `FALSE` to leave them alone.
reset_packages	`TRUE` to unload any packages loaded during a task (runs between each task), `FALSE` to leave packages alone.
reset_options	`TRUE` to reset global options to their original state between each task, `FALSE` otherwise. It is recommended to only set `reset_options = TRUE` if `reset_packages` is also `TRUE` because packages sometimes rely on options they set at loading time.
garbage_collection	`TRUE` to run garbage collection between tasks, `FALSE` to skip.
crashes_error	Positive integer scalar. If a worker exits `crashes_error` times in a row without completing all its assigned tasks, then the launcher throws an informative error. The reason for `crashes_error` is to avoid an infinite loop where a task crashes

a worker (through a segfault, maxing out memory, etc) but the worker always relaunches. To monitor the resources of crew workers, please see https://wlandau.github.io/crew/articles/logging.html.

tls — A TLS configuration object from crew_tls().

r_arguments — Optional character vector of command line arguments to pass to Rscript (non-Windows) or Rscript.exe (Windows) when starting a worker. Example: r_arguments = c("--vanilla", "--max-connections=32").

options_metrics — Either NULL to opt out of resource metric logging for workers, or an object from crew_options_metrics() to enable and configure resource metric logging for workers. For resource logging to run, the autometric R package version 0.1.0 or higher must be installed.

options_cluster — An options list from crew_options_pbs() with cluster-specific configuration options.

verbose — Deprecated. Use options_cluster instead.

command_submit — Deprecated. Use options_cluster instead.

command_terminate — Deprecated. Use options_cluster instead.

command_delete — Deprecated on 2024-01-08 (version 0.1.4.9001). Use command_terminate instead.

script_directory — Deprecated. Use options_cluster instead.

script_lines — Deprecated. Use options_cluster instead.

pbs_cwd — Deprecated. Use options_cluster instead.

pbs_log_output — Deprecated. Use options_cluster instead.

pbs_log_error — Deprecated. Use options_cluster instead.

pbs_log_join — Deprecated. Use options_cluster instead.

pbs_memory_gigabytes_required — Deprecated. Use options_cluster instead.

pbs_cores — Deprecated. Use options_cluster instead.

pbs_walltime_hours — Deprecated. Use options_cluster instead.

Details

WARNING: the crew.cluster PBS plugin is experimental and has not actually been tested on a PBS cluster. Please proceed with caution and report bugs to https://github.com/wlandau/crew.cluster.

To launch a PBS/TORQUE worker, this launcher creates a temporary job script with a call to crew::crew_worker() and submits it as an PBS job with qsub. To see most of the lines of the job script in advance, use the script() method of the launcher. It has all the lines except for the job name and the call to crew::crew_worker(), both of which will be inserted at the last minute when it is time to actually launch a worker.

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the crew launcher plugins in crew.cluster, and we would like to thank Michael Schubert for developing clustermq and releasing it under the permissive Apache License 2.0. See the NOTICE and README.md files in the crew.cluster source code for additional attribution.

See Also

Other pbs: crew_class_launcher_pbs, crew_controller_pbs(), crew_options_pbs()

---

crew_launcher_sge **[Maturing]** *Create a launcher with Sun Grid Engine (SGE) workers.*

Description

Create an R6 object to launch and maintain workers as Sun Grid Engine (SGE) jobs.

Usage

```
crew_launcher_sge(
  name = NULL,
  seconds_interval = 0.5,
  seconds_timeout = 60,
  seconds_launch = 86400,
  seconds_idle = 300,
  seconds_wall = Inf,
  tasks_max = Inf,
  tasks_timers = 0L,
  reset_globals = TRUE,
  reset_packages = FALSE,
  reset_options = FALSE,
  garbage_collection = FALSE,
  crashes_error = 5L,
  tls = crew::crew_tls(mode = "automatic"),
  r_arguments = c("--no-save", "--no-restore"),
  options_metrics = crew::crew_options_metrics(),
  options_cluster = crew.cluster::crew_options_sge(),
  verbose = NULL,
  command_submit = NULL,
  command_terminate = NULL,
  command_delete = NULL,
  script_directory = NULL,
  script_lines = NULL,
  sge_cwd = NULL,
  sge_envvars = NULL,
  sge_log_output = NULL,
```

```
  sge_log_error = NULL,
  sge_log_join = NULL,
  sge_memory_gigabytes_limit = NULL,
  sge_memory_gigabytes_required = NULL,
  sge_cores = NULL,
  sge_gpu = NULL
)
```

Arguments

name	Name of the launcher.
seconds_interval	Number of seconds between polling intervals waiting for certain internal synchronous operations to complete, such as checking `mirai::status()`.
seconds_timeout	Number of seconds until timing out while waiting for certain synchronous operations to complete, such as checking `mirai::status()`.
seconds_launch	Seconds of startup time to allow. A worker is unconditionally assumed to be alive from the moment of its launch until `seconds_launch` seconds later. After `seconds_launch` seconds, the worker is only considered alive if it is actively connected to its assign websocket.
seconds_idle	Maximum number of seconds that a worker can idle since the completion of the last task. If exceeded, the worker exits. But the timer does not launch until `tasks_timers` tasks have completed. See the `idletime` argument of `mirai::daemon()`. `crew` does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, so please allow enough idle time for a new worker to be delegated a new task.
seconds_wall	Soft wall time in seconds. The timer does not launch until `tasks_timers` tasks have completed. See the `walltime` argument of `mirai::daemon()`.
tasks_max	Maximum number of tasks that a worker will do before exiting. See the `maxtasks` argument of `mirai::daemon()`. `crew` does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, it is recommended to set `tasks_max` to a value greater than 1.
tasks_timers	Number of tasks to do before activating the timers for `seconds_idle` and `seconds_wall`. See the `timerstart` argument of `mirai::daemon()`.
reset_globals	`TRUE` to reset global environment variables between tasks, `FALSE` to leave them alone.
reset_packages	`TRUE` to unload any packages loaded during a task (runs between each task), `FALSE` to leave packages alone.
reset_options	`TRUE` to reset global options to their original state between each task, `FALSE` otherwise. It is recommended to only set `reset_options = TRUE` if `reset_packages` is also `TRUE` because packages sometimes rely on options they set at loading time.
garbage_collection	`TRUE` to run garbage collection between tasks, `FALSE` to skip.

`crashes_error` Positive integer scalar. If a worker exits `crashes_error` times in a row without completing all its assigned tasks, then the launcher throws an informative error. The reason for `crashes_error` is to avoid an infinite loop where a task crashes a worker (through a segfault, maxing out memory, etc) but the worker always relaunches. To monitor the resources of `crew` workers, please see https://wlandau.github.io/crew/articles/logging.html.

`tls` A TLS configuration object from `crew_tls()`.

`r_arguments` Optional character vector of command line arguments to pass to `Rscript` (non-Windows) or `Rscript.exe` (Windows) when starting a worker. Example: `r_arguments = c("--vanilla", "--max-connections=32")`.

`options_metrics` Either `NULL` to opt out of resource metric logging for workers, or an object from `crew_options_metrics()` to enable and configure resource metric logging for workers. For resource logging to run, the `autometric` R package version 0.1.0 or higher must be installed.

`options_cluster` An options list from `crew_options_sge()` with cluster-specific configuration options.

`verbose` Deprecated. Use `options_cluster` instead.

`command_submit` Deprecated. Use `options_cluster` instead.

`command_terminate` Deprecated. Use `options_cluster` instead.

`command_delete` Deprecated on 2024-01-08 (version 0.1.4.9001). Use `command_terminate` instead.

`script_directory` Deprecated. Use `options_cluster` instead.

`script_lines` Deprecated. Use `options_cluster` instead.

`sge_cwd` Deprecated. Use `options_cluster` instead.

`sge_envvars` Deprecated. Use `options_cluster` instead.

`sge_log_output` Deprecated. Use `options_cluster` instead.

`sge_log_error` Deprecated. Use `options_cluster` instead.

`sge_log_join` Deprecated. Use `options_cluster` instead.

`sge_memory_gigabytes_limit` Deprecated. Use `options_cluster` instead.

`sge_memory_gigabytes_required` Deprecated. Use `options_cluster` instead.

`sge_cores` Deprecated. Use `options_cluster` instead.

`sge_gpu` Deprecated. Use `options_cluster` instead.

Details

To launch a Sun Grid Engine (SGE) worker, this launcher creates a temporary job script with a call to `crew::crew_worker()` and submits it as an SGE job with `qsub`. To see most of the lines of the job script in advance, use the `script()` method of the launcher. It has all the lines except for the job name and the call to `crew::crew_worker()`, both of which will be inserted at the last minute when it is time to actually launch a worker.

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the crew launcher plugins in crew.cluster, and we would like to thank Michael Schubert for developing clustermq and releasing it under the permissive Apache License 2.0. See the NOTICE and README.md files in the crew.cluster source code for additional attribution.

See Also

Other sge: crew_class_launcher_sge, crew_class_monitor_sge, crew_controller_sge(), crew_monitor_sge(), crew_options_sge()

---

crew_launcher_slurm **[Experimental]** *Create a launcher with SLURM workers.*

Description

Create an R6 object to launch and maintain workers as SLURM jobs.

Usage

```
crew_launcher_slurm(
  name = NULL,
  seconds_interval = 0.5,
  seconds_timeout = 60,
  seconds_launch = 86400,
  seconds_idle = 300,
  seconds_wall = Inf,
  tasks_max = Inf,
  tasks_timers = 0L,
  reset_globals = TRUE,
  reset_packages = FALSE,
  reset_options = FALSE,
  garbage_collection = FALSE,
  crashes_error = 5L,
  tls = crew::crew_tls(mode = "automatic"),
  r_arguments = c("--no-save", "--no-restore"),
  options_metrics = crew::crew_options_metrics(),
  options_cluster = crew.cluster::crew_options_slurm(),
  verbose = NULL,
  command_submit = NULL,
  command_terminate = NULL,
  command_delete = NULL,
  script_directory = NULL,
  script_lines = NULL,
  slurm_log_output = NULL,
  slurm_log_error = NULL,
```

```
  slurm_memory_gigabytes_required = NULL,
  slurm_memory_gigabytes_per_cpu = NULL,
  slurm_cpus_per_task = NULL,
  slurm_time_minutes = NULL,
  slurm_partition = NULL
)
```

Arguments

name	Name of the launcher.
seconds_interval	Number of seconds between polling intervals waiting for certain internal synchronous operations to complete, such as checking `mirai::status()`.
seconds_timeout	Number of seconds until timing out while waiting for certain synchronous operations to complete, such as checking `mirai::status()`.
seconds_launch	Seconds of startup time to allow. A worker is unconditionally assumed to be alive from the moment of its launch until `seconds_launch` seconds later. After `seconds_launch` seconds, the worker is only considered alive if it is actively connected to its assign websocket.
seconds_idle	Maximum number of seconds that a worker can idle since the completion of the last task. If exceeded, the worker exits. But the timer does not launch until `tasks_timers` tasks have completed. See the `idletime` argument of `mirai::daemon()`. `crew` does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, so please allow enough idle time for a new worker to be delegated a new task.
seconds_wall	Soft wall time in seconds. The timer does not launch until `tasks_timers` tasks have completed. See the `walltime` argument of `mirai::daemon()`.
tasks_max	Maximum number of tasks that a worker will do before exiting. See the `maxtasks` argument of `mirai::daemon()`. `crew` does not excel with perfectly transient workers because it does not micromanage the assignment of tasks to workers, it is recommended to set `tasks_max` to a value greater than 1.
tasks_timers	Number of tasks to do before activating the timers for `seconds_idle` and `seconds_wall`. See the `timerstart` argument of `mirai::daemon()`.
reset_globals	`TRUE` to reset global environment variables between tasks, `FALSE` to leave them alone.
reset_packages	`TRUE` to unload any packages loaded during a task (runs between each task), `FALSE` to leave packages alone.
reset_options	`TRUE` to reset global options to their original state between each task, `FALSE` otherwise. It is recommended to only set `reset_options = TRUE` if `reset_packages` is also `TRUE` because packages sometimes rely on options they set at loading time.
garbage_collection	`TRUE` to run garbage collection between tasks, `FALSE` to skip.
crashes_error	Positive integer scalar. If a worker exits `crashes_error` times in a row without completing all its assigned tasks, then the launcher throws an informative error.

The reason for `crashes_error` is to avoid an infinite loop where a task crashes a worker (through a segfault, maxing out memory, etc) but the worker always relaunches. To monitor the resources of `crew` workers, please see https://wlandau.github.io/crew/articles/logging.html.

`tls` A TLS configuration object from `crew_tls()`.

`r_arguments` Optional character vector of command line arguments to pass to `Rscript` (non-Windows) or `Rscript.exe` (Windows) when starting a worker. Example: `r_arguments = c("--vanilla", "--max-connections=32")`.

`options_metrics`
Either `NULL` to opt out of resource metric logging for workers, or an object from `crew_options_metrics()` to enable and configure resource metric logging for workers. For resource logging to run, the `autometric` R package version 0.1.0 or higher must be installed.

`options_cluster`
An options list from `crew_options_slurm()` with cluster-specific configuration options.

`verbose` Deprecated. Use `options_cluster` instead.

`command_submit` Deprecated. Use `options_cluster` instead.

`command_terminate`
Deprecated. Use `options_cluster` instead.

`command_delete` Deprecated on 2024-01-08 (version 0.1.4.9001). Use `command_terminate` instead.

`script_directory`
Deprecated. Use `options_cluster` instead.

`script_lines` Deprecated. Use `options_cluster` instead.

`slurm_log_output`
Deprecated. Use `options_cluster` instead.

`slurm_log_error`
Deprecated. Use `options_cluster` instead.

`slurm_memory_gigabytes_required`
Deprecated. Use `options_cluster` instead.

`slurm_memory_gigabytes_per_cpu`
Deprecated. Use `options_cluster` instead.

`slurm_cpus_per_task`
Deprecated. Use `options_cluster` instead.

`slurm_time_minutes`
Deprecated. Use `options_cluster` instead.

`slurm_partition`
Deprecated. Use `options_cluster` instead.

Details

WARNING: the `crew.cluster` SLURM plugin is experimental and has not actually been tested on a SLURM cluster. Please proceed with caution and report bugs to https://github.com/wlandau/crew.cluster.

To launch a SLURM worker, this launcher creates a temporary job script with a call to `crew::crew_worker()` and submits it as an SLURM job with `sbatch`. To see most of the lines of the job script in advance, use the `script()` method of the launcher. It has all the lines except for the job name and the call to `crew::crew_worker()`, both of which will be inserted at the last minute when it is time to actually launch a worker.

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the `crew` launcher plugins in `crew.cluster`, and we would like to thank Michael Schubert for developing `clustermq` and releasing it under the permissive Apache License 2.0. See the `NOTICE` and `README.md` files in the `crew.cluster` source code for additional attribution.

See Also

Other slurm: `crew_class_launcher_slurm`, `crew_class_monitor_slurm`, `crew_controller_slurm()`, `crew_monitor_slurm()`, `crew_options_slurm()`

`crew_monitor_sge` **[Experimental]** *Create a SGE monitor object.*

Description

Create an `R6` object to monitor SGE cluster jobs.

Usage

```
crew_monitor_sge(
  verbose = TRUE,
  command_list = as.character(Sys.which("qstat")),
  command_terminate = as.character(Sys.which("qdel"))
)
```

Arguments

`verbose`	Deprecated. Use `options_cluster` instead.
`command_list`	Character of length 1, file path to the executable to list jobs.
`command_terminate`	Deprecated. Use `options_cluster` instead.

See Also

Other sge: `crew_class_launcher_sge`, `crew_class_monitor_sge`, `crew_controller_sge()`, `crew_launcher_sge()`, `crew_options_sge()`

crew_monitor_slurm [Experimental] *Create a SLURM monitor object.*

Description

Create an R6 object to monitor SLURM cluster jobs.

Usage

```
crew_monitor_slurm(
  verbose = TRUE,
  command_list = as.character(Sys.which("squeue")),
  command_terminate = as.character(Sys.which("scancel"))
)
```

Arguments

verbose	Deprecated. Use options_cluster instead.
command_list	Character of length 1, file path to the executable to list jobs.
command_terminate	Deprecated. Use options_cluster instead.

See Also

Other slurm: crew_class_launcher_slurm, crew_class_monitor_slurm, crew_controller_slurm(), crew_launcher_slurm(), crew_options_slurm()

crew_options_lsf [Experimental] *LSF options.*

Description

Set options for LSF job management.

Usage

```
crew_options_lsf(
  verbose = FALSE,
  command_submit = as.character(Sys.which("bsub")),
  command_terminate = as.character(Sys.which("bkill")),
  script_directory = tempdir(),
  script_lines = character(0L),
  cwd = getwd(),
  log_output = "/dev/null",
  log_error = "/dev/null",
```

```
  memory_gigabytes_limit = NULL,
  memory_gigabytes_required = NULL,
  cores = NULL
)
```

Arguments

verbose	Logical, whether to see console output and error messages when submitting worker.
command_submit	Character of length 1, file path to the executable to submit a worker job.
command_terminate	Character of length 1, file path to the executable to terminate a worker job. Set to "" to skip manually terminating the worker. Unless there is an issue with the platform, the job should still exit thanks to the NNG-powered network programming capabilities of mirai. Still, if you set command_terminate = "", you are assuming extra responsibility for manually monitoring your jobs on the cluster and manually terminating jobs as appropriate.
script_directory	Character of length 1, directory path to the job scripts. Just before each job submission, a job script is created in this folder. Script base names are unique to each launcher and worker, and the launcher deletes the script when the worker is manually terminated. tempdir() is the default, but it might not work for some systems. tools::R_user_dir("crew.cluster", which = "cache") is another reasonable choice.
script_lines	Optional character vector of additional lines to be added to the job script just after the more common flags. An example would be script_lines = "module load R" if your cluster supports R through an environment module.
cwd	Character of length 1, directory to launch the worker from (as opposed to the system default). cwd = "/home" translates to a line of #BSUB -cwd /home in the LSF job script. cwd = getwd() is the default, which launches workers from the current working directory. Set cwd = NULL to omit this line from the job script.
log_output	Character of length 1, file pattern to control the locations of the LSF worker log files. By default, both standard output and standard error go to the same file. log_output = "crew_log_%J.log" translates to a line of #BSUB -o crew_log_%J.log in the LSF job script, where %J is replaced by the job ID of the worker. The default is /dev/null to omit these logs. Set log_output = NULL to omit this line from the job script.
log_error	Character of length 1, file pattern for standard error. log_error = "crew_error_%J.err" translates to a line of #BSUB -e crew_error_%J.err in the LSF job script, where %J is replaced by the job ID of the worker. The default is /dev/null to omit these logs. Set log_error = NULL to omit this line from the job script.
memory_gigabytes_limit	Positive numeric vector, usually with a single element. Supply a vector to make memory_gigabytes_limit a retryable option (see the "Retryable options" section for details). memory_gigabytes_limit is the memory limit in gigabytes of the worker. memory_gigabytes_limit = 4 translates to a line of #BSUB -M 4G in the LSF job script. memory_gigabytes_limit = NULL omits this line.

`memory_gigabytes_required`
: Positive numeric vector, usually with a single element. Supply a vector to make `memory_gigabytes_required` a retryable option (see the "Retryable options" section for details).

  `memory_gigabytes_required` is the memory requirement in gigabytes. `memory_gigabytes_required = 4` translates to a line of `#BSUB -R 'rusage[mem=4G]'` in the LSF job script. `memory_gigabytes_required = NULL` omits this line.

`cores`
: Optional positive integer vector, usually with a single element. Supply a vector to make `cores` a retryable option (see the "Retryable options" section for details).

  `cores` is the number of CPU cores for the worker. `cores = 4` translates to a line of `#BSUB -n 4` in the LSF job script. `cores = NULL` omits this line.

Value

A classed list of options.

Retryable options

Arguments `memory_gigabytes_limit`, `memory_gigabytes_required`, and `cores` are retryable options. Each of these arguments be a vector where each successive element is used during a retry if the worker previously exited without completing all its assigned tasks. The last element of the vector is used if there are more retries than the length of the vector. Control the number of allowable retries with `crashes_error` argument of the controller.

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the `crew` launcher plugins in `crew.cluster`, and we would like to thank Michael Schubert for developing `clustermq` and releasing it under the permissive Apache License 2.0. See the `NOTICE` and `README.md` files in the `crew.cluster` source code for additional attribution.

See Also

Other lsf: `crew_class_launcher_lsf`, `crew_controller_lsf()`, `crew_launcher_lsf()`

Examples

```
crew_options_lsf()
```

`crew_options_pbs` **[Experimental]** *PBS options.*

Description

Set options for PBS job management.

Usage

```
crew_options_pbs(
  verbose = FALSE,
  command_submit = as.character(Sys.which("qsub")),
  command_terminate = as.character(Sys.which("qdel")),
  script_directory = tempdir(),
  script_lines = character(0L),
  cwd = TRUE,
  log_output = "/dev/null",
  log_error = NULL,
  log_join = TRUE,
  memory_gigabytes_required = NULL,
  cores = NULL,
  walltime_hours = 12
)
```

Arguments

`verbose`	Logical, whether to see console output and error messages when submitting worker.
`command_submit`	Character of length 1, file path to the executable to submit a worker job.
`command_terminate`	Character of length 1, file path to the executable to terminate a worker job. Set to `""` to skip manually terminating the worker. Unless there is an issue with the platform, the job should still exit thanks to the NNG-powered network programming capabilities of `mirai`. Still, if you set `command_terminate = ""`, you are assuming extra responsibility for manually monitoring your jobs on the cluster and manually terminating jobs as appropriate.
`script_directory`	Character of length 1, directory path to the job scripts. Just before each job submission, a job script is created in this folder. Script base names are unique to each launcher and worker, and the launcher deletes the script when the worker is manually terminated. `tempdir()` is the default, but it might not work for some systems. `tools::R_user_dir("crew.cluster", which = "cache")` is another reasonable choice.
`script_lines`	Optional character vector of additional lines to be added to the job script just after the more common flags. An example would be `script_lines = "module load R"` if your cluster supports R through an environment module.

`cwd` Logical of length 1, whether to set the working directory of the worker to the working directory it was launched from. `cwd = TRUE` is translates to a line of `cd "$O_WORKDIR"` in the job script. This line is inserted after the content of `script_lines` to make sure the `#PBS` directives are above system commands. `cwd = FALSE` omits this line.

`log_output` Character of length 1, file or directory path to PBS worker log files for standard output. `log_output = "VALUE"` translates to a line of `#PBS -o VALUE` in the PBS job script. The default is `/dev/null` to omit the logs. If you do supply a non-`/dev/null` value, it is recommended to supply a directory path with a trailing slash so that each worker gets its own set of log files.

`log_error` Character of length 1, file or directory path to PBS worker log files for standard error. `log_error = "VALUE"` translates to a line of `#PBS -e VALUE` in the PBS job script. The default of `NULL` omits this line. If you do supply a non-`/dev/null` value, it is recommended to supply a directory path with a trailing slash so that each worker gets its own set of log files.

`log_join` Logical, whether to join the stdout and stderr log files together into one file. `log_join = TRUE` translates to a line of `#PBS -j oe` in the PBS job script, while `log_join = FALSE` is equivalent to `#PBS -j n`. If `log_join = TRUE`, then `log_error` should be `NULL`.

`memory_gigabytes_required`
Optional positive numeric vector, usually with a single element. Supply a vector to make `memory_gigabytes_required` a retryable option (see the "Retryable options" section for details).

`memory_gigabytes_required` is the gigabytes of memory required to run the worker. `memory_gigabytes_required = 2.4` translates to a line of `#PBS -l mem=2.4gb` in the PBS job script. `memory_gigabytes_required = NULL` omits this line.

`cores` Optional positive integer vector, usually with a single element. Supply a vector to make `cores` a retryable option (see the "Retryable options" section for details).

`cores` is the number of cores for the worker ("slots" in PBS lingo). `cores = 4` translates to a line of `#PBS -l ppn=4` in the PBS job script. `cores = NULL` omits this line.

`walltime_hours` Numeric vector, usually with a single element. Supply a vector to make `cores` a retryable option (see the "Retryable options" section for details).

`walltime_hours` is the hours of wall time to request for the worker. `walltime_hours = 23` translates to a line of `#PBS -l walltime=23:00:00` in the job script. `walltime_hours = NULL` omits this line.

Value

A classed list of options.

Retryable options

Arguments `memory_gigabytes_required`, `cores`, and `walltime_hours` are retryable options. Each of these arguments be a vector where each successive element is used during a retry if the worker previously exited without completing all its assigned tasks. The last element of the vector is used

if there are more retries than the length of the vector. Control the number of allowable retries with `crashes_error` argument of the controller.

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the `crew` launcher plugins in `crew.cluster`, and we would like to thank Michael Schubert for developing `clustermq` and releasing it under the permissive Apache License 2.0. See the `NOTICE` and `README.md` files in the `crew.cluster` source code for additional attribution.

See Also

Other pbs: `crew_class_launcher_pbs`, `crew_controller_pbs()`, `crew_launcher_pbs()`

Examples

```
crew_options_pbs()
```

---

crew_options_sge **[Maturing]** *SGE options.*

Description

Set options for SGE job management.

Usage

```
crew_options_sge(
  verbose = FALSE,
  command_submit = as.character(Sys.which("qsub")),
  command_terminate = as.character(Sys.which("qdel")),
  script_directory = tempdir(),
  script_lines = character(0L),
  cwd = TRUE,
  envvars = FALSE,
  log_output = "/dev/null",
  log_error = NULL,
  log_join = TRUE,
  memory_gigabytes_limit = NULL,
  memory_gigabytes_required = NULL,
  cores = NULL,
  gpu = NULL
)
```

Arguments

verbose	Logical, whether to see console output and error messages when submitting worker.
command_submit	Character of length 1, file path to the executable to submit a worker job.
command_terminate	Character of length 1, file path to the executable to terminate a worker job. Set to "" to skip manually terminating the worker. Unless there is an issue with the platform, the job should still exit thanks to the NNG-powered network programming capabilities of mirai. Still, if you set command_terminate = "", you are assuming extra responsibility for manually monitoring your jobs on the cluster and manually terminating jobs as appropriate.
script_directory	Character of length 1, directory path to the job scripts. Just before each job submission, a job script is created in this folder. Script base names are unique to each launcher and worker, and the launcher deletes the script when the worker is manually terminated. tempdir() is the default, but it might not work for some systems. tools::R_user_dir("crew.cluster", which = "cache") is another reasonable choice.
script_lines	Optional character vector of additional lines to be added to the job script just after the more common flags. An example would be script_lines = "module load R" if your cluster supports R through an environment module.
cwd	Logical of length 1, whether to launch the worker from the current working directory (as opposed to the user home directory). cwd = TRUE translates to a line of #$ -cwd in the SGE job script. cwd = FALSE omits this line.
envvars	Logical of length 1, whether to forward the environment variables of the current session to the SGE worker. envvars = TRUE translates to a line of #$ -V in the SGE job script. envvars = FALSE omits this line.
log_output	Character of length 1, file or directory path to SGE worker log files for standard output. log_output = "VALUE" translates to a line of #$ -o VALUE in the SGE job script. The default is /dev/null to omit the logs. If you do supply a non-/dev/null value, it is recommended to supply a directory path with a trailing slash so that each worker gets its own set of log files.
log_error	Character of length 1, file or directory path to SGE worker log files for standard error. log_error = "VALUE" translates to a line of #$ -e VALUE in the SGE job script. The default of NULL omits this line. If you do supply a non-/dev/null value, it is recommended to supply a directory path with a trailing slash so that each worker gets its own set of log files.
log_join	Logical, whether to join the stdout and stderr log files together into one file. log_join = TRUE translates to a line of #$ -j y in the SGE job script, while log_join = FALSE is equivalent to #$ -j n. If log_join = TRUE, then log_error should be NULL.
memory_gigabytes_limit	Optional numeric vector, usually with a single element. Supply a vector to make memory_gigabytes_limit a retryable option (see the "Retryable options" section for details).

memory_gigabytes_limit is the maximum number of gigabytes of memory a worker is allowed to consume. If the worker consumes more than this level of memory, then SGE will terminate it. memory_gigabytes_limit = 5.7" translates to a line of "#$ -l h_rss=5.7G" in the SGE job script. memory_gigabytes_limit = NULL omits this line.

memory_gigabytes_required

Optional positive numeric vector, usually with a single element. Supply a vector to make memory_gigabytes_required a retryable option (see the "Retryable options" section for details).

memory_gigabytes_required is the gigabytes of memory required to run the worker. memory_gigabytes_required = 2.4 translates to a line of #$ -l m_mem_free=2.4G in the SGE job script. memory_gigabytes_required = NULL omits this line.

cores

Optional positive integer vector, usually with a single element. Supply a vector to make cores a retryable option (see the "Retryable options" section for details).

cores is the number of cores per worker ("slots" in SGE lingo). cores = 4 translates to a line of #$ -pe smp 4 in the SGE job script. cores = NULL omits this line.

gpu

Optional integer vector, usually with a single element. Supply a vector to make gpu a retryable option (see the "Retryable options" section for details).

gpu is the number of GPUs to request for the worker. gpu = 1 translates to a line of "#$ -l gpu=1" in the SGE job script. gpu = NULL omits this line.

Value

A classed list of options.

Retryable options

Arguments memory_gigabytes_limit, memory_gigabytes_required, cores, and gpu are retryable options. Each of these arguments be a vector where each successive element is used during a retry if the worker previously exited without completing all its assigned tasks. The last element of the vector is used if there are more retries than the length of the vector. Control the number of allowable retries with crashes_error argument of the controller.

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the crew launcher plugins in crew.cluster, and we would like to thank Michael Schubert for developing clustermq and releasing it under the permissive Apache License 2.0. See the NOTICE and README.md files in the crew.cluster source code for additional attribution.

See Also

Other sge: crew_class_launcher_sge, crew_class_monitor_sge, crew_controller_sge(), crew_launcher_sge(), crew_monitor_sge()

Examples

```
crew_options_sge()
```

`crew_options_slurm` **[Experimental]** *SLURM options.*

Description

Set options for SLURM job management.

Usage

```
crew_options_slurm(
  verbose = FALSE,
  command_submit = as.character(Sys.which("sbatch")),
  command_terminate = as.character(Sys.which("scancel")),
  script_directory = tempdir(),
  script_lines = character(0L),
  log_output = "/dev/null",
  log_error = "/dev/null",
  memory_gigabytes_required = NULL,
  memory_gigabytes_per_cpu = NULL,
  cpus_per_task = NULL,
  time_minutes = NULL,
  partition = NULL
)
```

Arguments

`verbose`	Logical, whether to see console output and error messages when submitting worker.
`command_submit`	Character of length 1, file path to the executable to submit a worker job.
`command_terminate`	Character of length 1, file path to the executable to terminate a worker job. Set to `""` to skip manually terminating the worker. Unless there is an issue with the platform, the job should still exit thanks to the NNG-powered network programming capabilities of `mirai`. Still, if you set `command_terminate = ""`, you are assuming extra responsibility for manually monitoring your jobs on the cluster and manually terminating jobs as appropriate.
`script_directory`	Character of length 1, directory path to the job scripts. Just before each job submission, a job script is created in this folder. Script base names are unique to each launcher and worker, and the launcher deletes the script when the worker is manually terminated. `tempdir()` is the default, but it might not work for some systems. `tools::R_user_dir("crew.cluster", which = "cache")` is another reasonable choice.

`script_lines` Optional character vector of additional lines to be added to the job script just after the more common flags. An example would be `script_lines = "module load R"` if your cluster supports R through an environment module.

`log_output` Character of length 1, file pattern to control the locations of the SLURM worker log files. By default, both standard output and standard error go to the same file. `log_output = "crew_log_%A.txt"` translates to a line of `#SBATCH --output=crew_log_%A.txt` in the SLURM job script, where `%A` is replaced by the job ID of the worker. The default is `/dev/null` to omit these logs. Set `log_output = NULL` to omit this line from the job script.

`log_error` Character of length 1, file pattern for standard error. `log_error = "crew_log_%A.txt"` translates to a line of `#SBATCH --error=crew_log_%A.txt` in the SLURM job script, where `%A` is replaced by the job ID of the worker. The default is `/dev/null` to omit these logs. Set `log_error = NULL` to omit this line from the job script.

`memory_gigabytes_required`

Positive numeric vector, usually with a single element. Supply a vector to make `memory_gigabytes_required` a retryable option (see the "Retryable options" section for details).

Each element is of `memory_gigabytes_required` the total number of gigabytes of memory required per node. `memory_gigabytes_required = 2.40123` translates to a line of `#SBATCH --mem=2041M` in the SLURM job script. `memory_gigabytes_required = NULL` omits this line.

`memory_gigabytes_per_cpu`

Positive numeric vector, usually with a single element. Supply a vector to make `memory_gigabytes_per_cpu` a retryable option (see the "Retryable options" section for details).

`memory_gigabytes_per_cpu` is the gigabytes of memory required per CPU. `memory_gigabytes_per_cpu = 2.40123` translates to a line of `#SBATCH --mem-per-cpu=2041M` in the SLURM job script. `memory_gigabytes_per_cpu = NULL` omits this line.

`cpus_per_task` Optional positive integer vector, usually with a single element. Supply a vector to make `cpus_per_task` a retryable option (see the "Retryable options" section for details).

`cpus_per_task` is the number of CPUs for the worker. `cpus_per_task = 4` translates to a line of `#SBATCH --cpus-per-task=4` in the SLURM job script. `cpus_per_task = NULL` omits this line.

`time_minutes` Numeric of length 1, usually with a single element. Supply a vector to make `time_minutes` a retryable option (see the "Retryable options" section for details).

`time_minutes` is the number of minutes to designate as the wall time of `crew` each worker instance on the SLURM cluster. `time_minutes = 60` translates to a line of `#SBATCH --time=60` in the SLURM job script. `time_minutes = NULL` omits this line.

`partition` Character of vector, usually with a single element. Supply a vector to make `partition` a retryable option (see the "Retryable options" section for details).

`partition` is the name of the SLURM partition to create workers on. `partition = "partition1,partition2"` translates to a line of `#SBATCH --partition=partition1,partition2` in the SLURM job script. `partition = NULL` omits this line.

Value

A classed list of options.

Retryable options

Arguments `memory_gigabytes_required`, `memory_gigabytes_per_cpu`, `cpus_per_task`, `time_minutes`, and `partition` are retryable options. Each of these arguments be a vector where each successive element is used during a retry if the worker previously exited without completing all its assigned tasks. The last element of the vector is used if there are more retries than the length of the vector. Control the number of allowable retries with `crashes_error` argument of the controller.

Attribution

The template files at https://github.com/mschubert/clustermq/tree/master/inst informed the development of the `crew` launcher plugins in `crew.cluster`, and we would like to thank Michael Schubert for developing `clustermq` and releasing it under the permissive Apache License 2.0. See the `NOTICE` and `README.md` files in the `crew.cluster` source code for additional attribution.

See Also

Other slurm: `crew_class_launcher_slurm`, `crew_class_monitor_slurm`, `crew_controller_slurm()`, `crew_launcher_slurm()`, `crew_monitor_slurm()`

Examples

```
crew_options_slurm()
```

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