

# Package ‘EfficientMaxEigenpair’

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**Type** Package

**Title** Efficient Initials for Computing the Maximal Eigenpair

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**Description** An implementation for using efficient initials to compute the maximal eigenpair in R. It provides three algorithms to find the efficient initials under two cases: the tridiagonal matrix case and the general matrix case. Besides, it also provides two algorithms for the next to the maximal eigenpair under these two cases.

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**URL** <http://github.com/mxjki/EfficientMaxEigenpair>

**BugReports** <http://github.com/mxjki/EfficientMaxEigenpair/issues>

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eff.ini.maxeig.general

*General matrix maximal eigenpair*

### Description

Calculate the maximal eigenpair for the general matrix.

### Usage

```
eff.ini.maxeig.general(A, v0_tilde = NULL, z0 = NULL, z0numeric, xi = 1,
    digit.thresh = 6)
```

### Arguments

A	The input general matrix.
v0_tilde	The unnormalized initial vector $\tilde{v}_0$ .
z0	The type of initial $z_0$ used to calculate the approximation of $\rho(Q)$ . There are three types: 'fixed', 'Auto' and 'numeric' corresponding to three choices of $z_0$ in paper.
z0numeric	The numerical value assigned to initial $z_0$ as an approximation of $\rho(Q)$ when $z_0='numeric'$ .
xi	The coefficient used to form the convex combination of $\delta_1^{-1}$ and $(v_0, -Q*v_0)_\mu$ , it should between 0 and 1.
digit.thresh	The precise level of output results.

### Value

A list of eigenpair object are returned, with components  $z$ ,  $v$  and  $iter$ .

z	The approximating sequence of the maximal eigenvalue.
v	The approximating eigenfunction of the corresponding eigenvector.
iter	The number of iterations.

**See Also**

[eff.ini.maxeig.tri](#) for the tridiagonal matrix maximal eigenpair by rayleigh quotient iteration algorithm. [eff.ini.maxeig.shift.inv.tri](#) for the tridiagonal matrix maximal eigenpair by shifted inverse iteration algorithm.

**Examples**

```
A = matrix(c(1, 1, 3, 2, 2, 2, 3, 1, 1), 3, 3)
eff.ini.maxeig.general(A, v0_tilde = rep(1, dim(A)[1]), z0 = 'fixed')

A = matrix(c(1, 1, 3, 2, 2, 2, 3, 1, 1), 3, 3)
eff.ini.maxeig.general(A, v0_tilde = rep(1, dim(A)[1]), z0 = 'Auto')

##Symmetrizing A converge to second largest eigenvalue
A = matrix(c(1, 3, 9, 5, 2, 14, 10, 6, 0, 11, 11, 7, 0, 0, 1, 8), 4, 4)
S = (t(A) + A)/2
N = dim(S)[1]
a = diag(S[-1, -N])
b = diag(S[-N, -1])
c = rep(NA, N)
c[1] = -diag(S)[1] - b[1]
c[2:(N - 1)] = -diag(S)[2:(N - 1)] - b[2:(N - 1)] - a[1:(N - 2)]
c[N] = -diag(S)[N] - a[N - 1]

z0ini = eff.ini.maxeig.tri(a, b, c, xi = 7/8)$z[1]
eff.ini.maxeig.general(A, v0_tilde = rep(1, dim(A)[1]), z0 = 'numeric',
z0numeric = 28 - z0ini)
```

---

```
eff.ini.maxeig.shift.inv.tri
```

*Tridiagonal matrix maximal eigenpair*

---

**Description**

Calculate the maximal eigenpair for the tridiagonal matrix by shifted inverse iteration algorithm.

**Usage**

```
eff.ini.maxeig.shift.inv.tri(a, b, c, xi = 1, digit.thresh = 6)
```

**Arguments**

- a            The lower diagonal vector.
- b            The upper diagonal vector.
- c            The shifted main diagonal vector. The corresponding unshift diagonal vector is  $-c(b[1] + c[1], a[1:N - 1] + b[2:N] + c[2:N], a[N] + c[N + 1])$  where  $N+1$  is the dimension of matrix.

xi	The coefficient used to form the convex combination of $\delta_1^{-1}$ and $(v_0, -Q * v_0)_\mu$ , it should be between 0 and 1.
digit.thresh	The precise level of output results.

**Value**

A list of eigenpair object are returned, with components  $z$ ,  $v$  and  $iter$ .

z	The approximating sequence of the maximal eigenvalue.
v	The approximating eigenfunction of the corresponding eigenvector.
iter	The number of iterations.

**See Also**

[eff.ini.maxeig.tri](#) for the tridiagonal matrix maximal eigenpair by rayleigh quotient iteration algorithm. [eff.ini.maxeig.general](#) for the general matrix maximal eigenpair.

**Examples**

```
a = c(1:7)^2
b = c(1:7)^2
c = rep(0, length(a) + 1)
c[length(a) + 1] = 8^2
eff.ini.maxeig.shift.inv.tri(a, b, c, xi = 1)
```

---

eff.ini.maxeig.tri      *Tridiagonal matrix maximal eigenpair*

---

**Description**

Calculate the maximal eigenpair for the tridiagonal matrix by rayleigh quotient iteration algorithm.

**Usage**

```
eff.ini.maxeig.tri(a, b, c, xi = 1, digit.thresh = 6)
```

**Arguments**

a	The lower diagonal vector.
b	The upper diagonal vector.
c	The shifted main diagonal vector. The corresponding unshift diagonal vector is $-c(b[1] + c[1], a[1:N - 1] + b[2:N] + c[2:N], a[N] + c[N + 1])$ where $N+1$ is the dimension of matrix.
xi	The coefficient used to form the convex combination of $\delta_1^{-1}$ and $(v_0, -Q * v_0)_\mu$ , it should be between 0 and 1.
digit.thresh	The precise level of output results.

**Value**

A list of eigenpair object are returned, with components  $z$ ,  $v$  and  $iter$ .

$z$	The approximating sequence of the maximal eigenvalue.
$v$	The approximating eigenfunction of the corresponding eigenvector.
$iter$	The number of iterations.

**See Also**

[eff.ini.maxeig.shift.inv.tri](#) for the tridiagonal matrix maximal eigenpair by shifted inverse iteration algorithm. [eff.ini.maxeig.general](#) for the general matrix maximal eigenpair.

**Examples**

```
a = c(1:7)^2
b = c(1:7)^2
c = rep(0, length(a) + 1)
c[length(a) + 1] = 8^2
eff.ini.maxeig.tri(a, b, c, xi = 1)
```

---

eff.ini.seceig.general

*General conservative matrix maximal eigenpair*

---

**Description**

Calculate the next to maximal eigenpair for the general conservative matrix.

**Usage**

```
eff.ini.seceig.general(Q, z0 = NULL, c1 = 1000, digit.thresh = 6)
```

**Arguments**

$Q$	The input general matrix.
$z_0$	The type of initial $z_0$ used to calculate the approximation of $\rho(Q)$ . There are two types: 'fixed' and 'Auto' corresponding to two choices of $z_0$ in paper.
$c_1$	A large constant.
<code>digit.thresh</code>	The precise level of output results.

**Value**

A list of eigenpair object are returned, with components  $z$ ,  $v$  and  $iter$ .

$z$	The approximating sequence of the maximal eigenvalue.
$v$	The approximating eigenfunction of the corresponding eigenvector.
$iter$	The number of iterations.

**Note**

The conservativity of matrix  $Q = (q_{ij})$  means that the sums of each row of matrix  $Q$  are all 0.

**See Also**

[eff.ini.seceig.tri](#) for the tridiagonal matrix next to the maximal eigenpair.

**Examples**

```
Q = matrix(c(-30, 1/5, 11/28, 55/3291, 30, -17, 275/42, 330/1097,
0, 84/5, -20, 588/1097, 0, 0, 1097/84, -2809/3291), 4, 4)
eff.ini.seceig.general(Q, z0 = 'Auto', digit.thresh = 5)
eff.ini.seceig.general(Q, z0 = 'fixed', digit.thresh = 5)
```

---

eff.ini.seceig.tri      *Tridiagonal matrix next to the maximal eigenpair*

---

**Description**

Calculate the next to maximal eigenpair for the tridiagonal matrix whose sums of each row should be 0.

**Usage**

```
eff.ini.seceig.tri(a, b, xi = 1, digit.thresh = 6)
```

**Arguments**

a	The lower diagonal vector.
b	The upper diagonal vector.
xi	The coefficient used in the improved initials to form the convex combination of $\delta_1^{-1}$ and $(v_0, -Q * v_0)_\mu$ , it should between 0 and 1.
digit.thresh	The precise level of output results.

**Value**

A list of eigenpair object are returned, with components  $z$ ,  $v$  and  $iter$ .

z	The approximating sequence of the maximal eigenvalue.
v	The approximating eigenfunction of the corresponding eigenvector.
iter	The number of iterations.

**Note**

The sums of each row of the input tridiagonal matrix should be 0.

**See Also**

[eff.ini.seceig.general](#) for the general conservative matrix next to the maximal eigenpair.

**Examples**

```
a = c(1:7)^2
b = c(1:7)^2

eff.ini.seceig.tri(a, b, xi = 0)
eff.ini.seceig.tri(a, b, xi = 1)
eff.ini.seceig.tri(a, b, xi = 2/5)
```

---

EfficientMaxEigenpair *EfficientMaxEigenpair: A package for computating the maximal eigenpair for a matrix.*

---

**Description**

The EfficientMaxEigenpair package provides some auxillary functions and five categories of important functions: [tridiag](#), [tri.sol](#), [find\\_deltak](#), [ray.quot.tri](#), [shift.inv.tri](#), [ray.quot.seceig.tri](#), [ray.quot.general](#), [ray.quot.seceig.general](#), [eff.ini.maxeig.tri](#), [eff.ini.maxeig.shift.inv.tri](#), [eff.ini.maxeig.general](#), [eff.ini.seceig.tri](#) and [eff.ini.seceig.general](#).

**EfficientMaxEigenpair functions**

[tridiag](#): generate tridiagonal matrix  $Q$  based on three input vectors.

[tri.sol](#): construct the solution of linear equation  $(-Q-zI)w=v$ .

[find\\_deltak](#): compute  $\delta_k$  for given vector  $v$  and matrix  $Q$ .

[ray.quot.tri](#): rayleigh quotient iteration algorithm to computing the maximal eigenpair of tridiagonal matrix  $Q$ .

[shift.inv.tri](#): shifted inverse iteration algorithm to computing the maximal eigenpair of tridiagonal matrix  $Q$ .

[ray.quot.seceig.tri](#): rayleigh quotient iteration algorithm to computing the next to maximal eigenpair of tridiagonal matrix  $Q$ .

[ray.quot.general](#): rayleigh quotient iteration algorithm to computing the maximal eigenpair of general matrix  $A$ .

[ray.quot.seceig.general](#): rayleigh quotient iteration algorithm to computing the next to maximal eigenpair of general matrix  $A$ .

[eff.ini.maxeig.tri](#): calculate the maximal eigenpair for the tridiagonal matrix by rayleigh quotient iteration algorithm.

[eff.ini.maxeig.shift.inv.tri](#): calculate the maximal eigenpair for the tridiagonal matrix by shifted inverse iteration algorithm.

[eff.ini.maxeig.general](#): calculate the maximal eigenpair for the general matrix.

`eff.ini.seceig.tri`: calculate the next to maximal eigenpair for the tridiagonal matrix whose sums of each row should be 0.

`eff.ini.seceig.general`: calculate the next to maximal eigenpair for the general conservative matrix.

---

`find_deltak`                      *Compute  $\delta_k$*

---

### Description

Compute  $\delta_k$  for given vector  $v$  and matrix  $Q$ .

### Usage

```
find_deltak(Q, v)
```

### Arguments

$Q$                       The given tridiagonal matrix.  
 $v$                       The column vector on the right hand of equation.

### Value

A list of  $\delta_k$  for given vector  $v$  and matrix  $Q$ .

### Examples

```
a = c(1:7)^2
b = c(1:7)^2
c = rep(0, length(a) + 1)
c[length(a) + 1] = 8^2
N = length(a)
Q = tridiag(b, a, -c(b[1] + c[1]), a[1:N - 1] + b[2:N] + c[2:N], a[N] + c[N + 1])
find_deltak(Q, v=rep(1,dim(Q)[1]))
```

---

`ray.quot.general`                      *Rayleigh quotient iteration*

---

### Description

Rayleigh quotient iteration algorithm to computing the maximal eigenpair of general matrix  $A$ .

### Usage

```
ray.quot.general(A, mu, v0_tilde, zstart, digit.thresh = 6)
```



**Arguments**

A	The input matrix to find the maximal eigenpair.
mu	A vector.
v0_tilde	The unnormalized initial vector $\tilde{v}_0$ .
zstart	The initial $z_0$ as an approximation of $\rho(Q)$ .
digit.thresh	The precise level of output results.

**Value**

A list of eigenpair object are returned, with components  $z$ ,  $v$  and  $iter$ .

z	The approximating sequence of the maximal eigenvalue.
v	The approximating eigenfunction of the corresponding eigenvector.
iter	The number of iterations.

**Examples**

```
A = matrix(c(1, 1, 3, 2, 2, 2, 3, 1, 1), 3, 3)
ray.quot.general(A, mu=rep(1,dim(A)[1]), v0_tilde=rep(1,dim(A)[1]), zstart=6,
digit.thresh = 6)
```

---

```
ray.quot.seceig.general
      Rayleigh quotient iteration
```

---

**Description**

Rayleigh quotient iteration algorithm to computing the maximal eigenpair of matrix Q.

**Usage**

```
ray.quot.seceig.general(Q, mu, v0_tilde, zstart, digit.thresh = 6)
```

**Arguments**

Q	The input matrix to find the maximal eigenpair.
mu	A vector.
v0_tilde	The unnormalized initial vector $\tilde{v}_0$ .
zstart	The initial $z_0$ as an approximation of $\rho(Q)$ .
digit.thresh	The precise level of output results.

**Value**

A list of eigenpair object are returned, with components  $z$ ,  $v$  and  $iter$ .

$z$	The approximating sequence of the maximal eigenvalue.
$v$	The approximating sequence of the corresponding eigenvector.
$iter$	The number of iterations.

**Examples**

```
Q = matrix(c(1, 1, 3, 2, 2, 2, 3, 1, 1), 3, 3)
ray.quot.seceig.general(Q, mu=rep(1,dim(Q)[1]), v0_tilde=rep(1,dim(Q)[1]), zstart=6,
digit.thresh = 6)
```

---

ray.quot.seceig.tri     *Rayleigh quotient iteration for Tridiagonal matrix*

---

**Description**

Rayleigh quotient iteration algorithm to computing the next to maximal eigenpair of tridiagonal matrix  $Q$ .

**Usage**

```
ray.quot.seceig.tri(Q, mu, v0_tilde, zstart, digit.thresh = 6)
```

**Arguments**

$Q$	The input matrix to find the maximal eigenpair.
$\mu$	A vector.
$v0\_tilde$	The unnormalized initial vector $\tilde{v}_0$ .
$zstart$	The initial $z_0$ as an approximation of $\rho(Q)$ .
$digit.thresh$	The precise level of output results.

**Value**

A list of eigenpair object are returned, with components  $z$ ,  $v$  and  $iter$ .

$z$	The approximating sequence of the maximal eigenvalue.
$v$	The approximating eigenfunction of the corresponding eigenvector.
$iter$	The number of iterations.

**Examples**

```

a = c(1:7)^2
b = c(1:7)^2
c = rep(0, length(a) + 1)
c[length(a) + 1] = 8^2
N = length(a)
Q = tridiag(b, a, -c(b[1] + c[1]), a[1:N - 1] + b[2:N] + c[2:N], a[N] + c[N + 1])
ray.quot.seceig.tri(Q, mu=rep(1,dim(Q)[1]), v0_tilde=rep(1,dim(Q)[1]), zstart=6,
  digit.thresh = 6)

```

ray.quot.tri

*Rayleigh quotient iteration for Tridiagonal matrix***Description**

Rayleigh quotient iteration algorithm to computing the maximal eigenpair of tridiagonal matrix  $Q$ .

**Usage**

```
ray.quot.tri(Q, mu, v0_tilde, zstart, digit.thresh = 6)
```

**Arguments**

<code>Q</code>	The input matrix to find the maximal eigenpair.
<code>mu</code>	A vector.
<code>v0_tilde</code>	The unnormalized initial vector $\tilde{v}_0$ .
<code>zstart</code>	The initial $z_0$ as an approximation of $\rho(Q)$ .
<code>digit.thresh</code>	The precise level of output results.

**Value**

A list of eigenpair object are returned, with components  $z$ ,  $v$  and  $iter$ .

<code>z</code>	The approximating sequence of the maximal eigenvalue.
<code>v</code>	The approximating eigenfunction of the corresponding eigenvector.
<code>iter</code>	The number of iterations.

**Examples**

```

a = c(1:7)^2
b = c(1:7)^2
c = rep(0, length(a) + 1)
c[length(a) + 1] = 8^2
N = length(a)
Q = tridiag(b, a, -c(b[1] + c[1]), a[1:N - 1] + b[2:N] + c[2:N], a[N] + c[N + 1])
ray.quot.tri(Q, mu=rep(1,dim(Q)[1]), v0_tilde=rep(1,dim(Q)[1]), zstart=6,
  digit.thresh = 6)

```

---

 shift.inv.tri

*Shifted inverse iteration algorithm for Tridiagonal matrix*


---

### Description

Shifted inverse iteration algorithm algorithm to computing the maximal eigenpair of tridiagonal matrix  $Q$ .

### Usage

```
shift.inv.tri(Q, mu, v0_tilde, zstart, digit.thresh = 6)
```

### Arguments

<code>Q</code>	The input matrix to find the maximal eigenpair.
<code>mu</code>	A vector.
<code>v0_tilde</code>	The unnormalized initial vector $\tilde{v}_0$ .
<code>zstart</code>	The initial $z_0$ as an approximation of $\rho(Q)$ .
<code>digit.thresh</code>	The precise level of output results.

### Value

A list of eigenpair object are returned, with components  $z$ ,  $v$  and  $iter$ .

<code>z</code>	The approximating sequence of the maximal eigenvalue.
<code>v</code>	The approximating eigenfunction of the corresponding eigenvector.
<code>iter</code>	The number of iterations.

### Examples

```
a = c(1:7)^2
b = c(1:7)^2
c = rep(0, length(a) + 1)
c[length(a) + 1] = 8^2
N = length(a)
Q = tridiag(b, a, -c(b[1] + c[1]), a[1:N - 1] + b[2:N] + c[2:N], a[N] + c[N + 1]))
shift.inv.tri(Q, mu=rep(1,dim(Q)[1]), v0_tilde=rep(1,dim(Q)[1]), zstart=6,
  digit.thresh = 6)
```

---

tri.sol	<i>Solve the linear equation <math>(-Q-zI)w=v</math>.</i>
---------	---

---

**Description**

Construct the solution of linear equation  $(-Q-zI)w=v$ .

**Usage**

```
tri.sol(Q, z, v)
```

**Arguments**

Q	The given tridiagonal matrix.
z	The Rayleigh shift.
v	The column vector on the right hand of equation.

**Value**

A solution sequence  $w$  to the equation  $(-Q-zI)w=v$ .

**Examples**

```
a = c(1:7)^2
b = c(1:7)^2
c = rep(0, length(a) + 1)
c[length(a) + 1] = 8^2
N = length(a)
zstart = 6
Q = tridiag(b, a, -c(b[1] + c[1]), a[1:N - 1] + b[2:N] + c[2:N], a[N] + c[N + 1])
tri.sol(Q, z=zstart, v=rep(1,dim(Q)[1]))
```

---

tridiag	<i>Tridiagonal matrix</i>
---------	---------------------------

---

**Description**

Generate tridiagonal matrix Q based on three input vectors.

**Usage**

```
tridiag(upper, lower, main)
```

**Arguments**

upper	The upper diagonal vector.
lower	The lower diagonal vector.
main	The main diagonal vector.

**Value**

A tridiagonal matrix is returned.

**Examples**

```
a = c(1:7)^2
b = c(1:7)^2
c = -c(1:8)^2
tridiag(b, a, c)
```

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